

# A Novel Improved Soft Switching PWM DC-DC Converter

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**Abstract:** A new zero-voltage switching (ZVS) pulse width modulation (PWM) DC-DC converter using MOSFETs is proposed in this paper. The proposed converter achieves ZVS with reduction in voltage and current stresses across switches to improve the efficiency by minimizing the switching and conduction losses. The predicted operation principles and theoretical analysis of the presented converter are verified with a prototype of a 360 W, 50 V/6 V and 100 kHz PWM half bridge buck converter. Additionally, at full output power in the proposed soft switching converter the overall efficiency, which is 80% in the hard switching case, increases to about 95%.

**Keywords:** PWM, DC-DC converter, ZVS.

## I. INTRODUCTION

With advance in VLSI technology, smaller, more powerful digital system is available. It requires power supply with higher power density, lower profile and higher efficiency. To further increase the processing speed and efficiency, operating voltage is continuously reduced. With advance in VLSI technology, smaller, more powerful digital system is available. It requires power supply with higher power density, lower profile and higher efficiency. To further increase the processing speed and efficiency, operating voltage is continuously reduced with increase in operating current. Also fast transient response and smaller size for a given power supply becomes very important [1][2]. PWM topologies have been widely used for this application. Unfortunately, hold up time requirement put huge penalties on the performance of these topologies. Also, high switching loss limited the power density achievable for these topologies. Excessive switching loss prohibited higher switching frequency. Soft switching converters employing two transformers have been researched in recent years for power converters to reduce switching losses [3]. High frequency PWM DC-DC converters have been widely used in industry due to their high power density, fast response and control simplicity [4]. Especially at high frequencies and high power levels, it is necessary to use advanced soft switching techniques to reduce switching losses. In this paper, a simple and new topology is introduced to achieve higher efficiency as compared to the conventional converter. This proposed converter utilizes three clamped capacitors in the primary side of the transformer to provide low output voltage.

The capacitor used in series with the transformer provides better dead time control. The resonance between two capacitors in arm of the bridge and the leakage inductance of the

transformer make the switches turned on/off under zero voltage switching (ZVS). It's simple configuration, make ease to control. With less number of components, this converter becomes more economical and attractive as compared to other previously researched converter. In the reference papers, different soft switching techniques are used to reduce switching

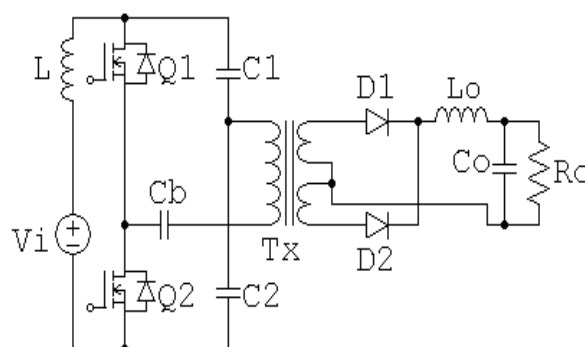


Fig 1. Proposed soft switching dc-dc converter

losses and the operations are analysed properly. But the duration of current flowing through the body diode of MOSFET switches is not controlled in past work.

In the reference papers, different soft switching techniques are used to reduce switching losses and the operations are analysed properly. But the duration of current flowing through the body diode of MOSFET switches is not controlled in past work. During transition periods, high input current may flow through the switches, in result conduction losses may occur. This problem can be avoided by using an inductor in series with the supply.

This proposed converter is designed to solve the above problems. The following points have to follow in the paper:

- description of topology used and design process
- design of blocking capacitor for dead time control
- design of transformer leakage inductance so that the stored energy should transfer properly to supply during off time.

## II. OPERATION PRINCIPLES AND ANALYSIS

The following assumptions are made to simplify the circuit operations

- secondary side leakage inductance is neglected;

- capacitance of the blocking capacitor is taken more as compared to other two capacitors used in this circuit;
- capacitances of other two capacitors are taken as same value;
- turn ratio of transformer is taken asymmetrical;
- to make magnetizing current ripple free, magnetizing inductance  $L_m$  is chosen as high value;
- current flowing through transformer is continuous;

The proposed converter scheme is shown in Fig.1. The circuit scheme includes two MOSFET switches  $Q_1$  and  $Q_2$ . Two clamp capacitors  $C_1$  and  $C_2$ . The transformer  $T_x$  denotes the combination of the magnetizing inductance  $L_m$ , the leakage inductance  $L_{lk}$  and the ideal transformer with transformer winding-ratio  $n:1$ . The proposed dc-dc converter is designed through AC link as energy transfer devices. In steady-state, the proposed converter has four operation states during one switching cycle. The key waveforms and the equivalent circuits of each operation state are shown in Fig.2 and Fig.3, respectively.

*Mode 1 ( $t_0-t_1$ )* : At  $t = t_0$ , MOSFET  $Q_1$  is turned on by providing proper gate pulse. Now current starts to flow through the transformer. With the induction property, the diode  $D_2$  is compelled to conduct. Resonant condition occurs by the magnetizing inductance  $L_m$  and equivalent capacitance of  $C_b$  and  $C_1$ . But the resonant period is less, so high peak current and voltage stresses cannot appear across the switch  $Q_1$ .

The voltage and current expression will be as

$$i_L(t-t_0) = \frac{V}{L} [P \sin \sqrt{k_1}(t-t_0) + Q \sin \sqrt{k_2}(t-t_0)] \quad (1)$$

$$v_{C1}(t-t_0) = \frac{V}{LC_1} * \frac{P}{\sqrt{k_1}} \cos \sqrt{k_1}(t-t_0) - \frac{V}{LC_1} * \frac{Q}{\sqrt{k_2}} \cos \sqrt{k_2}(t-t_0) \quad (2)$$

$$v_{C2}(t-t_0) = V - v_L(t-t_0) - v_{C1}(t-t_0) \quad (3)$$

Where  $P$ ,  $Q$ ,  $k_1$  and  $k_2$  are function of  $L$ ,  $L_p$ ,  $C_1$ ,  $C_2$ ,  $C_b$ , which is a big expression.

The switch is turned on under ZVS due to capacitor  $C_1$ , and turned off under ZCS due to transformer leakage inductance  $L_p$ . This mode is ended when capacitor  $C_1$  completely discharge its energy to capacitor  $C_b$  and  $L_1$ . At this moment input current completely flow through capacitor  $C_1$ , providing current through the switch equal to zero. So at this moment switch  $Q_1$  can be turned off under ZCS. At end of this mode,  $C_b$  charged up to  $C_{b1}$  opposite to that of its initial value.

At  $t = t_1$ ,  $i_L(t_1) = I_{L1}$ ,  $v_{C1} = 0$ ,  $v_{C_b} = v_{C_{b1}}$ ,  $v_{C2} = v_{C2}$ ,

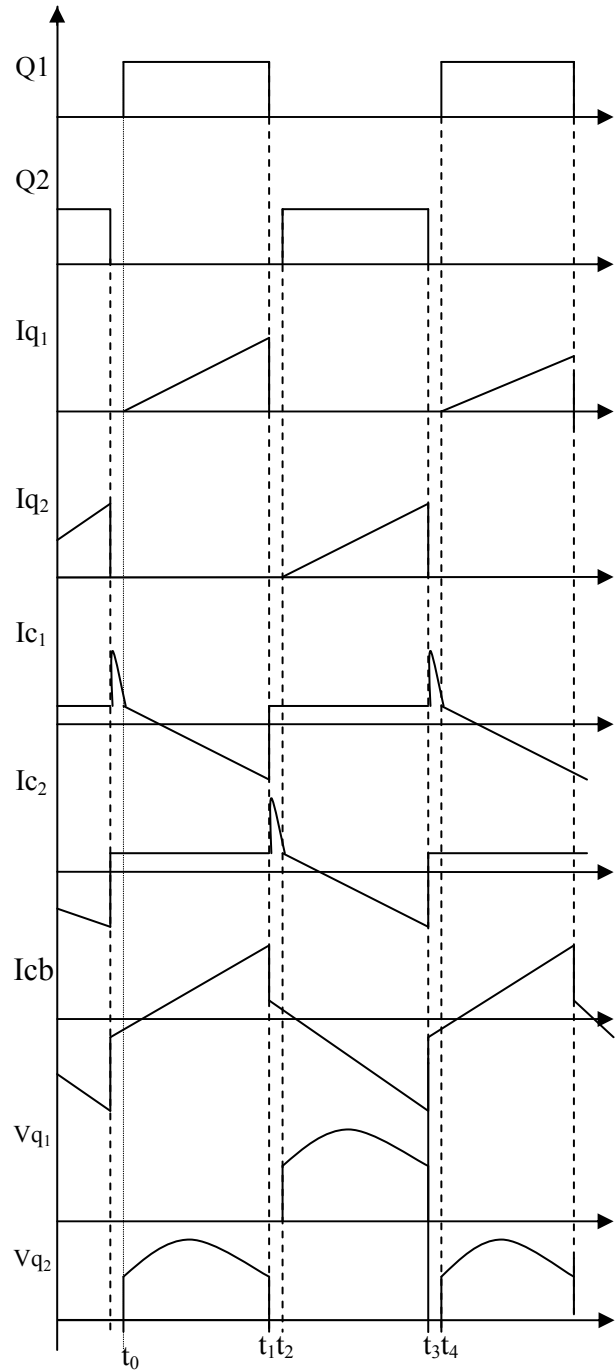
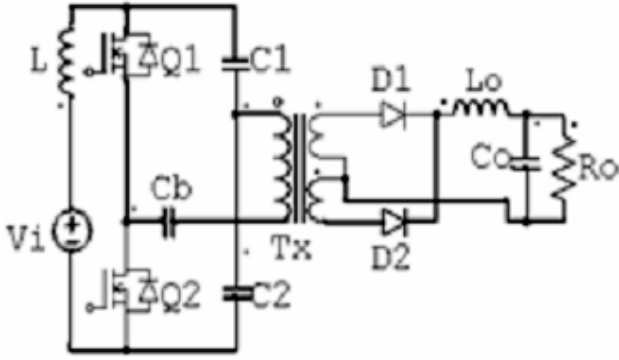


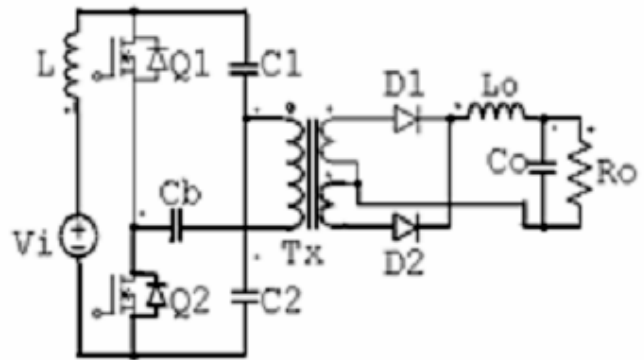
Fig. 2. Key waveforms of the proposed converter

*Mode 2 ( $t_1-t_2$ )* : At  $t = t_1$ , stored energy of inductor is forced the body diode of switch to conduct and inductor discharged its stored energy through  $C_2$ - $D_{Q2}$ - $C_b$ . Resonance occur between leakage inductance  $L_p$  and capacitors  $C_2$  and  $C_b$ . However, the resonant period is not more than the dead time. Dead time is controlled by capacitor  $C_b$ . This mode ends at  $t_2$ , when current through  $C_b$  becomes zero i.e. this blocking capacitor is charged upto its maximum value.

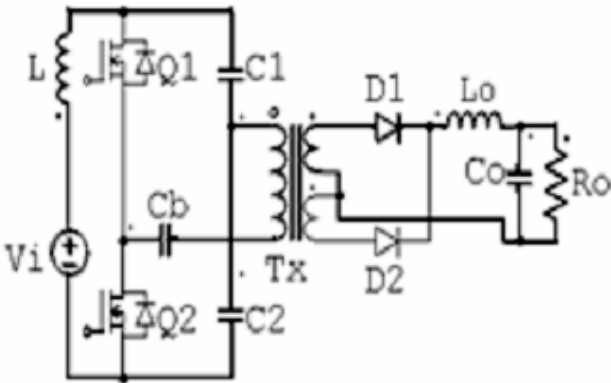
The voltage and current expressions for this mode are given below.



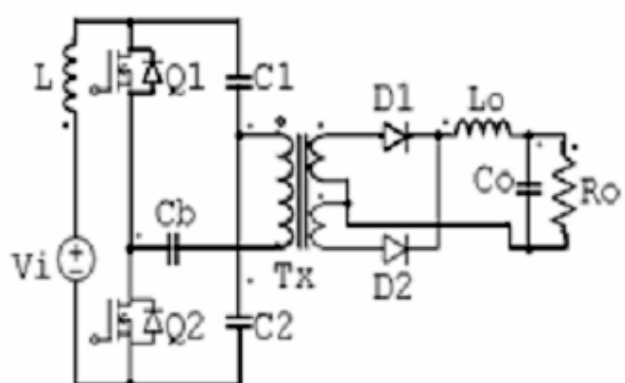
Mode 1



Mode 2



Mode 3



Mode 4

Fig. 3

Modes of Operation

$$i_L(t-t_1) = \frac{V-v_{C2}}{L} \left[ R \sin \sqrt{k_3}(t-t_1) + S \sin \sqrt{k_4}(t-t_1) \right] + I_{L1} \left[ R \cos \sqrt{k_3}(t-t_1) + S \cos \sqrt{k_4}(t-t_1) \right] \quad (4)$$

$$i_{Lp}(t-t_1) = I_{L1} \cos \frac{1}{\sqrt{L_p C_e}}(t-t_1) - \frac{v_{Cb1} + v_{C2}}{Z_1} \sin \frac{1}{\sqrt{L_p C_e}}(t-t_1) \quad (5)$$

$$v_{Cb}(t-t_1) = \frac{I_{L1} \sqrt{L_p C_e}}{C_b} \sin \frac{1}{\sqrt{L_p C_e}}(t-t_1) + (v_{Cb1} + v_{C2}) C_e \cos \frac{1}{\sqrt{L_p C_e}}(t-t_1) \quad (6)$$

$$v_{C2}(t-t_1) = \frac{V-v_{C2}}{LC_2} \left[ -\frac{R \cos \sqrt{k_3}(t-t_1)}{\sqrt{k_3}} - \frac{S \cos \sqrt{k_4}(t-t_1)}{\sqrt{k_4}} \right] + \frac{I_{L1}}{C_2} \left[ \frac{R \sin \sqrt{k_3}(t-t_1)}{\sqrt{k_3}} + \frac{S \sin \sqrt{k_4}(t-t_1)}{\sqrt{k_4}} \right] \quad (7)$$

Now the voltage across capacitor  $C_2$  can be expressed as  $v_{C2}(t-t_1) = V - v_L(t-t_1) - v_{C1}(t-t_1)$  (8)

where  $R, S, k_3, k_4$ , are function of  $L, L_p, C_1, C_2, C_b$ ,

$$\text{and } Z_1 = \sqrt{\frac{L_p}{C_e}}, \quad C_e = \frac{C_b C_2}{C_b + C_2}$$

**Mode 3 (  $t_2-t_3$  ) :** This mode starts with switch  $Q_2$  turned-on under ZVS, diode  $D_1$  on with  $D_2$  off. This mode will come to end with capacitor  $C_b$  charged upto peak value, but with opposite polarity as compared to previous mode. This mode is ended when capacitor  $C_2$  completely discharge its energy to capacitor  $C_b$  and  $L_p$ . At this moment input current completely

flow through capacitor  $C_2$ , providing current through the switch  $Q_2$  equal to zero. So at this moment switch  $Q_2$  can be turned off under ZCS. At end of this mode,  $C_b$  charged up to  $C_{b2}$  opposite to that of its initial value.

The voltage and current expression for this mode is given as follows,

$$i_L(t-t_2) = I_{L2} \left[ T \cos \sqrt{k_5}(t-t_2) + U \cos \sqrt{k_6}(t-t_2) \right] + \left( \frac{V - v_{C1}}{L} + \frac{v_{C2}}{L} \right) \left[ T \sin \sqrt{k_5}(t-t_2) + U \sin \sqrt{k_6}(t-t_2) \right] \dots (9)$$

At the end of this mode, current through transformer is zero.

$$v_{C2}(t-t_2) = I_{L2} \left[ \frac{T \sin \sqrt{k_5}(t-t_2)}{\sqrt{k_5}} + \frac{U \sin \sqrt{k_6}(t-t_2)}{\sqrt{k_6}} \right] - \left( \frac{V - v_{C1}}{L} + \frac{v_{C2}}{L_p} \right) * \left[ \frac{T \cos \sqrt{k_5}(t-t_2)}{\sqrt{k_5}} + \frac{U \cos \sqrt{k_6}(t-t_2)}{\sqrt{k_6}} \right] \quad (10)$$

$$v_{C1}(t-t_2) = V - v_L(t-t_2) - v_{C2}(t-t_2) \quad (11)$$

Where  $T, U, k_5, k_6$  are function of  $L, L_p, C_1, C_2, C_b$ ,

*Mode 4 ( $t_3-t_4$ )* : The transformer start to transfer stored energy to secondary side as well as to capacitor  $C_1$ , which ensure the continuous flow of current at the output. Then the rectified diode  $D_2$  will start to conduct, while diode  $D_1$  will be turned off under ZVS. The body diode of the switch  $Q_1$  is turned on due to the energy transferring property of inductor in the same direction in which it get charged. The mode ends at  $t_4$ , when current through  $C_b$  becomes zero i.e. this blocking capacitor is charged upto its maximum value.

The voltage and current expression for this mode is given as follow:

$$i_{Lp}(t-t_3) = I_{Lp1} \cos \frac{1}{\sqrt{L_p C_e}}(t-t_3) + \frac{v_{Cb2}}{Z_2} \sin \frac{1}{\sqrt{L_p C_e}}(t-t_3) \quad (12)$$

$$i_L(t-t_3) = \frac{V}{Z_3} \sin \frac{1}{\sqrt{L C_e}}(t-t_3) - \frac{I_{Lp1}}{L C_1} \left[ A \sin \sqrt{k_8}(t-t_3) + B \sin \sqrt{k_9}(t-t_3) \right] + \frac{v_{Cb2}}{Z_2} \left[ C \cos \sqrt{k_8}(t-t_3) + D \cos \sqrt{k_9}(t-t_3) \right] \quad (13)$$

$$v_{Cb}(t-t_3) = \frac{I_{Lp1} \sqrt{L_p C_e}}{C_b} \sin \frac{1}{\sqrt{L_p C_e}}(t-t_3) - \frac{v_{Cb2} \sqrt{L_p C_e}}{Z_2} \sin \frac{1}{\sqrt{L_p C_e}}(t-t_3) \quad (14)$$

Where  $Z_2 = \sqrt{\frac{L_p}{C_e}}$ ,  $C_e' = \frac{C_1 C_2}{C_1 + C_2}$ ,  $C_e = \frac{C_b C_1}{C_b + C_1}$  and  $Z_3 = \sqrt{\frac{L}{C_e}}$

The constants used in the expressions i.e. A, B, C, and D are functions of  $L, L_p, C_1, C_2, C_b$ ,

At the end of this mode  $v_{Cb} = -v_{Cbmax}$ ,

#### IV. DESIGN PROCEDURE

The advent of the switching regulator has greatly reduced the size, weight and volume of power conversion circuitry, while improving both the speed of response and efficiency. It is easy to minimize resistance because we have available very low ESR capacitors, low on-resistance MOSFETs and low series-resistance inductors..

The design should take into account the following considerations:

1.  $C_b \geq C_1$  and  $C_2$ : If this condition is satisfied, dead time control can be done smoothly, so that turn-on and turn-off losses can be reduced i.e.

$$t_{12} \geq \frac{C_b (v_{Cbmax} - v_{Cb1})}{I_{Cb1}} \quad (15)$$

2. The transformer leakage inductance  $L_p$  should such a value that it can discharge its energy completely to  $C_b, C_1, C_2$  and load:

$$\frac{1}{2} L_p I_{Lpmax}^2 = \frac{1}{2} C_b v_{Cb}^2 + \frac{1}{2} C_1 v_{C1}^2 + \frac{1}{2} C_2 v_{C2}^2 \quad (16)$$

*Transformer Design:*

The inductor-transformer should be designed to minimize the leakage inductance, ac winding losses, and core losses.

When the transformer is designed to operate in discontinuous mode the total inductance is lower than in continuous mode, and the size of the transformer may be smaller. But the peak currents will be at least twice the average current, therefore ac winding losses and core losses are the predominant factors rather than the dc losses and core saturation. The total losses are minimized when core losses and winding losses are approximately the same value.

-Core selection:

To reduce the core losses, ferrite-P material is usually the preferred material for discontinuous transformers with operating switching frequencies higher than 100Khz.

The window shape of the core should be as wide as possible to minimize the number of layers and therefore minimize the ac winding losses and the leakage inductance. E-type cores with an internal air-gap are the best choice for low cost and lower

leakage inductance. Winding techniques to minimize leakage inductance, ac losses and EMI noise:

To minimize the ac losses, leakage inductance and the EMI noise, particular attention has to be paid to the design of the primary and secondary windings of the transformer.

The primary winding should be designed for less than three layers, thus minimizing the winding capacitance and the leakage inductance of the transformer. In high switching frequency applications an additional insulating layer between windings is usually used.

If the transformer has multiple secondary windings, the highest power secondary should be closest to the primary of the transformer. For high power applications, a split primary construction is typically used to reduce the leakage inductance. To avoid high ac winding losses due to the skin effect (at high frequency currents tend to flow close to the surface of the conductor), Litz wire or Foil windings are typically used. Litz wire for power applications is usually made with a few small diameter wires twisted together in a strand, and few of these strands twisted into bigger strands. Shielding tape or an additional winding between primary and secondaries is typically used to reduce the capacitive coupling of common mode noise between primary and secondary. The end of this additional winding has to be connected to ground or to the high input voltage of the transformer.

#### V. BASIC CONVERTER FEATURES

The features of the proposed soft switching converter are briefly summarized as follows:

1. The proposed converter is configured in a simple way.
2. It has low cost and ease to control.
3. The converter acts as a conventional PWM converter during most of the switching cycle.
4. All the switches used in this circuit are switched on and off under ZVS and ZCS.
5. The converter has higher overall efficiency and wide load range control.
6. This converter has dead time control capability.
7. Input current is ripple freed.

#### III. SIMULATION AND EXPERIMENTAL RESULTS

To demonstrate the validity and performance of the proposed converter was tested experimentally and was simulated. The 360 W 50 V/6 V converter is chosen for the investigations. Ro

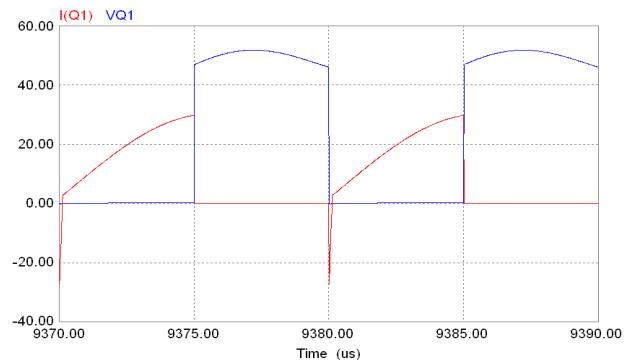
TABLE I  
COMPONENTS USED IN THE PROPOSED CONVERTER

Component	Value/Model	
	Simulation	Experiment
MOSFET Switch, Q <sub>1</sub>	Ideal	IRFP250N
MOSFET Switch, Q <sub>2</sub>	Ideal	IRFP250N
Schottky Diode, D <sub>1</sub>	Ideal	MBR60L45CTG
Schottky Diode, D <sub>2</sub>	Ideal	MBR60L45CTG
Input Inductor, L <sub>1</sub>	2μH	2μH
Capacitor, C <sub>1</sub>	4μF	4μF
Capacitor, C <sub>2</sub>	4μF	4μF
Blocking Capacitor, C <sub>b</sub>	6μF	6μF
Output Inductor, L <sub>o</sub>	3μH	3μH
Output Capacitor, C <sub>o</sub>	20μF	20μF

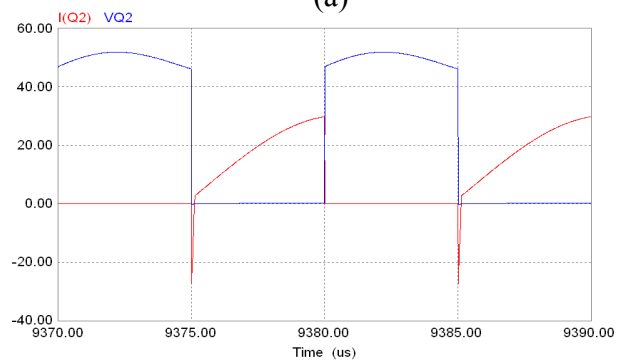
= 0.1Ω, L<sub>m</sub> = 5μH, n<sub>1</sub>:n<sub>2</sub> = 4 : 1, switching frequency = 100 kHz. Simulated waveforms and experimental results are shown in the fig. 4 and fig.5.

#### A. Simulation Results

The simulated converter delivers a load of 360W with efficiency of 95.2 %. The simulated waveforms shown in the fig. 4(a) and 4(b), are obtained by using PSIM. From the simulated waveform, it can be seen that both switches are turned on and turned off ZVS and ZCS. In fig. 6 graph between efficiency and load current is shown. The experimental oscillograms shown in fig. 5(a) and 5(b) are obtained from operating soft switching converter with a camera. All parameters details are given in Table I and II.



(a)



(b)

Fig. 4(a & b) Simulated current and voltage waveforms of switch Q1 and Q2.

#### B. Experimental Results

The experimental result shows that the proposed converter is properly designed with ZVS for the 100 kHz under full load condition.

TABLE 2  
TRANSFORMER DESIGN FOR EXPERIMENTAL CONVERTER

Parameter	Name	Value	Unit
	Transformer	Core	RM10×1
	Inductance	L <sub>M</sub>	5 μH
	Trans Ratio	N <sub>p</sub> :N <sub>s</sub> :N <sub>t</sub>	4:1:1
	Leakage Inductance	L <sub>lk</sub>	0.1 μH

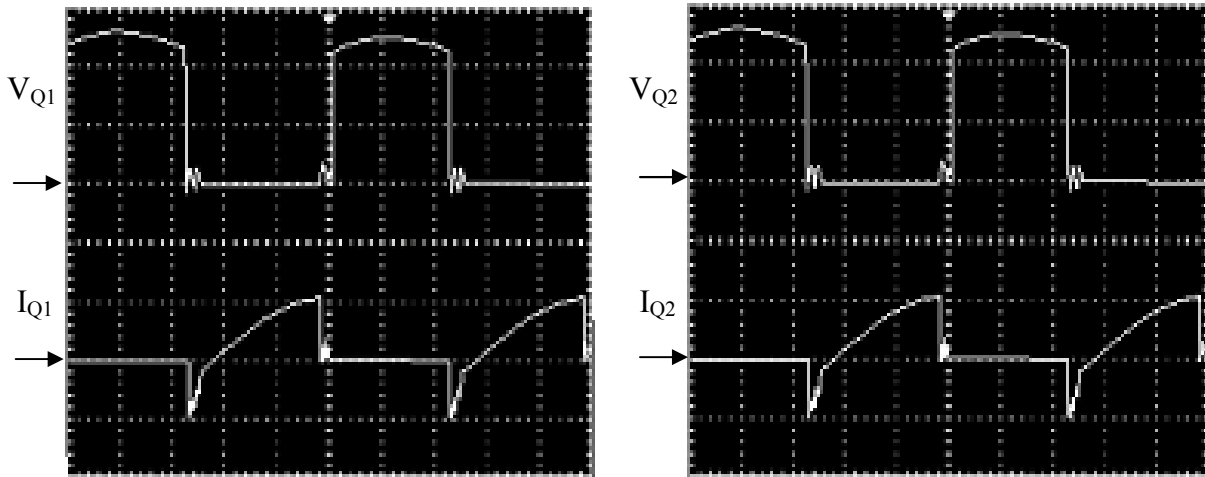


Fig. 5(a). Experimental voltage and current waveforms of switch Q1 ( $V_{Q1}$ : 10V/div,  $I_{Q1}$ : 10A/div), 5(b) Experimental voltage and current waveforms of switch Q2 ( $V_{Q2}$ : 10V/div,  $I_{Q2}$ : 10A/div)

**C. Conclusion:**

The proposed converter designed has several features and advantages: high efficiency, high power density, least size due to smaller components used, cheaper and faster switching frequency of 100 kHz. It provides better efficiency by reducing switching and conduction losses.

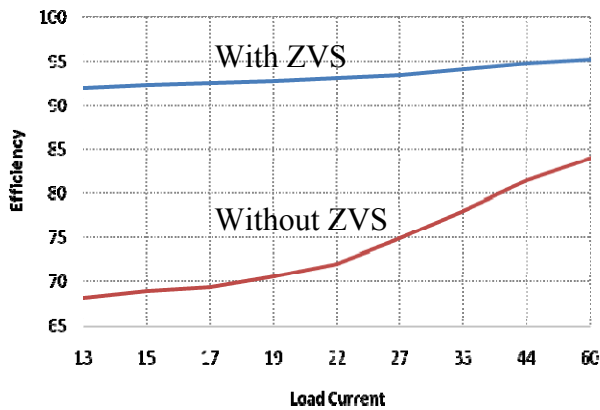


Fig.6 Graph between efficiency and load current

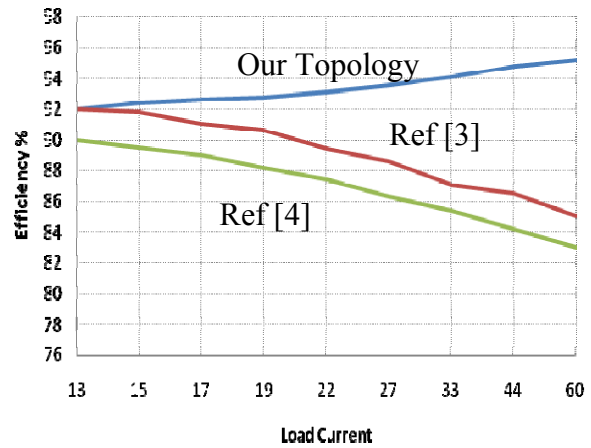


Fig 7 Efficiency Vs Load Current (Comparison of our topology with topology used in ref [3] and [4]).

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