

# Uniform Numerical Method For a Class of Parameterized Singularly Perturbed Problems

Jugal Mohapatra

Department of Mathematics  
NIT Rourkela

ICMMCS  
December 08-10, 2014  
Department of Mathematics  
IIT Madras



# Outline

- 1 **Introduction**
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid



# Outline

- 1 Introduction
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid
- 2 Parameterized SPP on Adaptive grid



# Outline

- 1 Introduction
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid
- 2 Parameterized SPP on Adaptive grid
- 3 Numerical Experiments



# Outline

- 1 Introduction
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid
- 2 Parameterized SPP on Adaptive grid
- 3 Numerical Experiments
- 4 Conclusion



# Outline

- 1 Introduction
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid
- 2 Parameterized SPP on Adaptive grid
- 3 Numerical Experiments
- 4 Conclusion
- 5 References





# Outline

- 1 **Introduction**
  - Singular Perturbation Problem (SPP)
  - Shishkin mesh and Adaptive grid
- 2 Parameterized SPP on Adaptive grid
- 3 Numerical Experiments
- 4 Conclusion
- 5 References



# Singular Perturbation Problems





# Singular Perturbation Problems

- Singular perturbed problems (SPPs) arise in several branches of **engineering and applied mathematics** including **convection-dominated flow** problems with large Reynolds numbers in **fluid mechanics**, modelling **semi-conductor device** and problems in **population dynamics** etc.



# Singular Perturbation Problems

- Singular perturbed problems (SPPs) arise in several branches of **engineering and applied mathematics** including **convection-dominated flow** problems with large Reynolds numbers in **fluid mechanics**, modelling **semi-conductor device** and problems in **population dynamics** etc.
- Differential equations where the highest order derivative is multiplied by an arbitrarily small parameter  $\varepsilon$  known as the **singular perturbation parameter**.

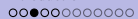




# Singular Perturbation Problems

- Singular perturbed problems (SPPs) arise in several branches of **engineering and applied mathematics** including **convection-dominated flow** problems with large Reynolds numbers in **fluid mechanics**, modelling **semi-conductor device** and problems in **population dynamics** etc.
- Differential equations where the highest order derivative is multiplied by an arbitrarily small parameter  $\varepsilon$  known as the **singular perturbation parameter**.
- Solutions of these problems possess **boundary layers** which are **thin regions** in the neighborhood of the boundary of the domain, where the gradients of the solutions steepen as  $\varepsilon \rightarrow 0$ .





# Motivation





# Motivation

$$\begin{cases} \varepsilon u''(x) + u'(x) = 0, & x \in (0, 1), \\ u(0) = 1, & u(1) = 0. \end{cases}$$



# Motivation

$$\begin{cases} \varepsilon u''(x) + u'(x) = 0, & x \in (0, 1), \\ u(0) = 1, & u(1) = 0. \end{cases}$$

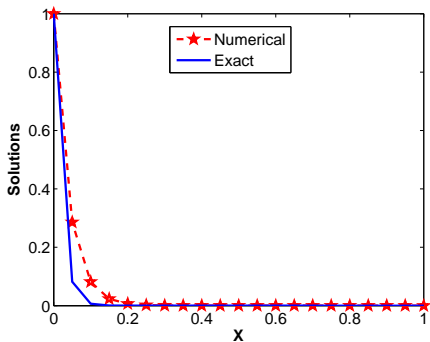
Solving this BVP on **uniform mesh**,



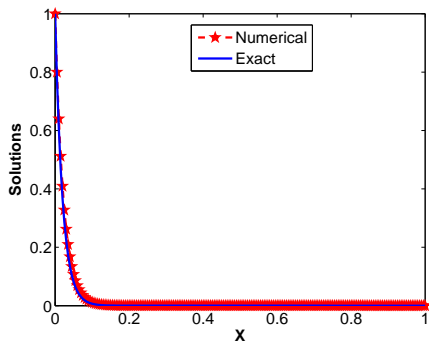
# Motivation

$$\begin{cases} \varepsilon u''(x) + u'(x) = 0, & x \in (0, 1), \\ u(0) = 1, & u(1) = 0. \end{cases}$$

Solving this BVP on **uniform mesh**,



(a)  $N = 20$ .



(b)  $N = 200$ .

Figure: Numerical solution with exact solution for  $\varepsilon = 1e - 2$ .





# Motivation





# Motivation

- Numerical experiments conducted on **uniform mesh**, reveal that the **classical methods** usually fail to decrease the maximum point-wise error as the mesh is refined, until the **mesh parameter** ( $N$ ) and the **perturbation parameter** ( $\varepsilon$ ) have the same order of magnitude.



# Motivation

- Numerical experiments conducted on **uniform mesh**, reveal that the **classical methods** usually fail to decrease the maximum point-wise error as the mesh is refined, until the **mesh parameter** ( $N$ ) and the **perturbation parameter** ( $\varepsilon$ ) have the same order of magnitude.
- This is unacceptable due to the vast **computational cost**.



# Motivation

- Numerical experiments conducted on **uniform mesh**, reveal that the **classical methods** usually fail to decrease the maximum point-wise error as the mesh is refined, until the **mesh parameter** ( $N$ ) and the **perturbation parameter** ( $\varepsilon$ ) have the same order of magnitude.
- This is unacceptable due to the vast **computational cost**.
- This **drawback** motivates to develop the concept of  **$\varepsilon$ -uniform numerical methods**.



# Motivation

- Numerical experiments conducted on **uniform mesh**, reveal that the **classical methods** usually fail to decrease the maximum point-wise error as the mesh is refined, until the **mesh parameter** ( $N$ ) and the **perturbation parameter** ( $\varepsilon$ ) have the same order of magnitude.
- This is unacceptable due to the vast **computational cost**.
- This **drawback** motivates to develop the concept of  **$\varepsilon$ -uniform numerical methods**.
- A numerical method is  **$\varepsilon$ -uniformly convergent**, if

$$\sup_{0 < \varepsilon \leq 1} \|u - U^N\|_{\Omega^N} \leq C N^{-p}, \quad p > 0,$$

where  $C$  is independent of **mesh points, mesh size and the parameter  $\varepsilon$** .

$u$  – Exact solution,  $U^N$  – Numerical approximation.

$N$  – No. of mesh elements,  $p$  – Rate of convergence.



# Objective



# Objective

- The main **objective** of the work is to **develop, analyze and improve** the  $\varepsilon$ -uniform *upwind methods* resolving parametrized boundary-value problems using nonuniform mesh.



# Objective

- The main **objective** of the work is to **develop, analyze and improve** the  $\varepsilon$ -uniform *upwind methods* resolving parametrized boundary-value problems using nonuniform mesh.

Two kinds of nonuniform meshes are discussed .



# Objective

- The main **objective** of the work is to **develop, analyze and improve** the  $\varepsilon$ -uniform *upwind methods* resolving parametrized boundary-value problems using nonuniform mesh.

Two kinds of nonuniform meshes are discussed .

- *Shishkin mesh*





# Objective

- The main **objective** of the work is to **develop, analyze and improve** the  $\varepsilon$ -uniform *upwind methods* resolving parametrized boundary-value problems using nonuniform mesh.

Two kinds of nonuniform meshes are discussed .

- *Shishkin mesh*
- *Adaptive grid*



# Outline

- 1 **Introduction**
  - Singular Perturbation Problem (SPP)
  - **Shishkin mesh and Adaptive grid**
- 2 Parameterized SPP on Adaptive grid
- 3 Numerical Experiments
- 4 Conclusion
- 5 References



# The Shishkin mesh



# The Shishkin mesh

This mesh has a transition point  $\sigma$  where

$$\sigma = \min \left\{ \frac{1}{2}, \sigma_0 \varepsilon \ln N \right\}.$$

where  $\sigma_0$  depends on the convective coefficient.



# The Shishkin mesh

This mesh has a transition point  $\sigma$  where

$$\sigma = \min \left\{ \frac{1}{2}, \sigma_0 \varepsilon \ln N \right\}.$$

where  $\sigma_0$  depends on the convective coefficient.

- Divide the  $[0, 1]$  into two subdomains  $[0, \sigma)$  and  $[\sigma, 1]$ .
- Divide the  $[0, \sigma)$  into  $N/2$  equal subdivisions of width  $h$  and  $[\sigma, 1]$  into  $N/2$  equal subdivisions of width  $H$ .



# The Shishkin mesh

This mesh has a transition point  $\sigma$  where

$$\sigma = \min \left\{ \frac{1}{2}, \sigma_0 \varepsilon \ln N \right\}.$$

where  $\sigma_0$  depends on the convective coefficient.

- Divide the  $[0, 1]$  into two subdomains  $[0, \sigma)$  and  $[\sigma, 1]$ .
- Divide the  $[0, \sigma)$  into  $N/2$  equal subdivisions of width  $h$  and  $[\sigma, 1]$  into  $N/2$  equal subdivisions of width  $H$ .
- Hence, the Shishkin mesh  $\Omega_\sigma^N = \{x_i\}_{i=0}^N$ , where  $x_0 = 0, x_N = 1$  and the mesh width  $h_i := x_i - x_{i-1}$  satisfy  $h_i = h$  for  $i = 1, \dots, N/2$  and  $h_i = H$  for  $i = N/2 + 1, \dots, N$ .



# The Shishkin mesh

This mesh has a transition point  $\sigma$  where

$$\sigma = \min \left\{ \frac{1}{2}, \sigma_0 \varepsilon \ln N \right\}.$$

where  $\sigma_0$  depends on the convective coefficient.

- Divide the  $[0, 1]$  into two subdomains  $[0, \sigma)$  and  $[\sigma, 1]$ .
- Divide the  $[0, \sigma)$  into  $N/2$  equal subdivisions of width  $h$  and  $[\sigma, 1]$  into  $N/2$  equal subdivisions of width  $H$ .
- Hence, the Shishkin mesh  $\Omega_\sigma^N = \{x_i\}_{i=0}^N$ , where  $x_0 = 0, x_N = 1$  and the mesh width  $h_i := x_i - x_{i-1}$  satisfy  $h_i = h$  for  $i = 1, \dots, N/2$  and  $h_i = H$  for  $i = N/2 + 1, \dots, N$ .
- The **piecewise-uniform mesh** is entirely determined by the two chosen parameters  $N$  and  $\sigma$ .



# The Shishkin mesh





# The Shishkin mesh

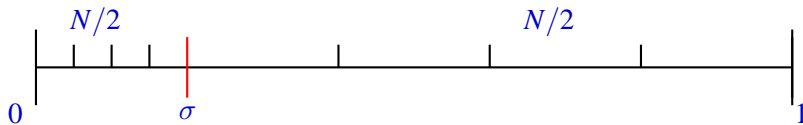


Figure: Shishkin mesh with  $N=8$  for left layer.

# The Shishkin mesh

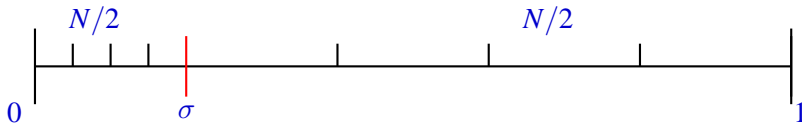


Figure: Shishkin mesh with  $N=8$  for left layer.

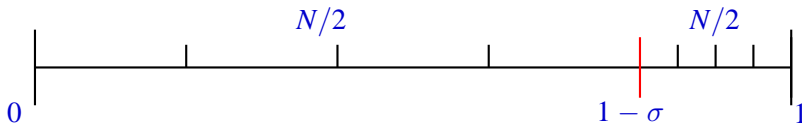
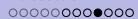


Figure: Shishkin mesh with  $N=8$  for right layer.



# Adaptive grid



# Adaptive grid

A grid  $\Omega^N$  is said to be equidistributing, if

$$\int_{x_{j-1}}^{x_j} M(u(s), s) ds = \int_{x_j}^{x_{j+1}} M(u(s), s) ds, \quad j = 1, \dots, N-1, \quad (1)$$

where  $M(u(x), x) > 0$  is called the monitor function.



# Adaptive grid

A grid  $\Omega^N$  is said to be equidistributing, if

$$\int_{x_{j-1}}^{x_j} M(u(s), s) ds = \int_{x_j}^{x_{j+1}} M(u(s), s) ds, \quad j = 1, \dots, N-1, \quad (1)$$

where  $M(u(x), x) > 0$  is called the monitor function.

Equivalently, (1) can be expressed as

$$\int_{x_{j-1}}^{x_j} M(u(s), s) ds = \frac{1}{N} \int_0^1 M(u(s), s) ds, \quad j = 1, \dots, N-1. \quad (2)$$



# Adaptive grid

A grid  $\Omega^N$  is said to be equidistributing, if

$$\int_{x_{j-1}}^{x_j} M(u(s), s) ds = \int_{x_j}^{x_{j+1}} M(u(s), s) ds, \quad j = 1, \dots, N-1, \quad (1)$$

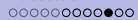
where  $M(u(x), x) > 0$  is called the monitor function.

Equivalently, (1) can be expressed as

$$\int_{x_{j-1}}^{x_j} M(u(s), s) ds = \frac{1}{N} \int_0^1 M(u(s), s) ds, \quad j = 1, \dots, N-1. \quad (2)$$

In practice, the monitor function is often based on a simple function of the **derivatives of the solution**.





# Adaptive grid



# Adaptive grid

Here, we consider **the arc-length monitor function**

$$M(u(x), x) = \sqrt{1 + (u'(x))^2}. \quad (3)$$





# Adaptive grid

Here, we consider **the arc-length monitor function**

$$M(u(x), x) = \sqrt{1 + (u'(x))^2}. \quad (3)$$

In other words, we can construct the mesh from (1) as the solution of the following nonlinear system of equations:

$$\begin{cases} (x_{j+1} - x_j)^2 + (U_{j+1}^N - U_j^N)^2 = (x_j - x_{j-1})^2 + (U_j^N - U_{j-1}^N)^2, \\ \quad \quad \quad j = 1, \dots, N - 1, \\ x_0 = 0, \quad x_N = 1. \end{cases} \quad (4)$$



# Adaptive grid

Here, we consider the arc-length monitor function

$$M(u(x), x) = \sqrt{1 + (u'(x))^2}. \quad (3)$$

In other words, we can construct the mesh from (1) as the solution of the following nonlinear system of equations:

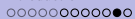
$$\begin{cases} (x_{j+1} - x_j)^2 + (U_{j+1}^N - U_j^N)^2 = (x_j - x_{j-1})^2 + (U_j^N - U_{j-1}^N)^2, \\ \quad \quad \quad j = 1, \dots, N-1, \\ x_0 = 0, \quad x_N = 1. \end{cases} \quad (4)$$

The discrete problem and (4) are solved simultaneously to obtain the solution  $U_j^N$  and the grids  $x_j$ .



# Adaptive algorithm





# Adaptive algorithm

- 1 **Initialize mesh-** Construct uniform mesh  $\{0, 1/N, 2/N, \dots, 1\}$ .



# Adaptive algorithm

- 1 **Initialize mesh-** Construct uniform mesh  $\{0, 1/N, 2/N, \dots, 1\}$ .
- 2 For each  $k = 0, 1, 2, \dots$ , compute the numerical solution  $u_i^{(k)}$  from the discrete problem.  
Let  $h_i^{(k)} = x_i^{(k)} - x_{i-1}^{(k)}$  for each  $i$ .



# Adaptive algorithm

- 1 **Initialize mesh**- Construct uniform mesh  $\{0, 1/N, 2/N, \dots, 1\}$ .
- 2 For each  $k = 0, 1, 2, \dots$ , compute the numerical solution  $u_i^{(k)}$  from the discrete problem.  
Let  $h_i^{(k)} = x_i^{(k)} - x_{i-1}^{(k)}$  for each  $i$ .

- 3 Now

$$l_i^{(k)} = h_i^{(k)} \sqrt{1 + (D^- u_i^{(k)})^2} = \sqrt{(u_i^{(k)} - u_{i-1}^{(k)})^2 + (h_i^{(k)})^2}$$

be the arc-length between the points  $(x_{i-1}^{(k)}, u_{i-1}^{(k)})$  and  $(x_i^{(k)}, u_i^{(k)})$  in the piecewise continuous solution  $u^{(k)}$ . Now the total length is  $L^{(k)} := \sum_{i=1}^N l_i^{(k)}$ .



# Adaptive algorithm

- 1 **Initialize mesh**- Construct uniform mesh  $\{0, 1/N, 2/N, \dots, 1\}$ .
- 2 For each  $k = 0, 1, 2, \dots$ , compute the numerical solution  $u_i^{(k)}$  from the discrete problem.  
Let  $h_i^{(k)} = x_i^{(k)} - x_{i-1}^{(k)}$  for each  $i$ .

- 3 Now

$$l_i^{(k)} = h_i^{(k)} \sqrt{1 + (D^- u_i^{(k)})^2} = \sqrt{(u_i^{(k)} - u_{i-1}^{(k)})^2 + (h_i^{(k)})^2}$$

be the arc-length between the points  $(x_{i-1}^{(k)}, u_{i-1}^{(k)})$  and  $(x_i^{(k)}, u_i^{(k)})$  in the piecewise continuous solution  $u^{(k)}$ . Now the total length is  $L^{(k)} := \sum_{i=1}^N l_i^{(k)}$ .

- 4 **Test mesh**-Choose a constant  $C_0 > 1$  to be user-chosen constant. Stopping criteria is if

$$\frac{\max l_i^{(k)}}{L^{(k)}} \leq \frac{C_0}{N},$$

holds true, then **STOP**. Otherwise, continue to step-5.



# Adaptive algorithm

- 1 **Initialize mesh**- Construct uniform mesh  $\{0, 1/N, 2/N, \dots, 1\}$ .
- 2 For each  $k = 0, 1, 2, \dots$ , compute the numerical solution  $u_i^{(k)}$  from the discrete problem.  
Let  $h_i^{(k)} = x_i^{(k)} - x_{i-1}^{(k)}$  for each  $i$ .

- 3 Now

$$l_i^{(k)} = h_i^{(k)} \sqrt{1 + (D^- u_i^{(k)})^2} = \sqrt{(u_i^{(k)} - u_{i-1}^{(k)})^2 + (h_i^{(k)})^2}$$

be the arc-length between the points  $(x_{i-1}^{(k)}, u_{i-1}^{(k)})$  and  $(x_i^{(k)}, u_i^{(k)})$  in the piecewise continuous solution  $u^{(k)}$ . Now the total length is  $L^{(k)} := \sum_{i=1}^N l_i^{(k)}$ .

- 4 **Test mesh**-Choose a constant  $C_0 > 1$  to be user-chosen constant. Stopping criteria is if

$$\frac{\max l_i^{(k)}}{L^{(k)}} \leq \frac{C_0}{N},$$

holds true, then **STOP**. Otherwise, continue to step-5.

- 5 **New mesh**-Choose points  $\{0 = x_0^{(k+1)} < x_1^{(k+1)} < x_2^{(k+1)} < \dots x_N^{(k+1)} = 1\}$  such that for each  $i$ , the distance from  $(x_{i-1}^{(k+1)}, u_{i-1}^{(k+1)})$  and  $(x_i^{(k+1)}, u_i^{(k+1)})$ , measured along the polygonal solution curve  $u^{(k)}(x)$ , equals  $L^{(k)}/N$ . Return to step-2.



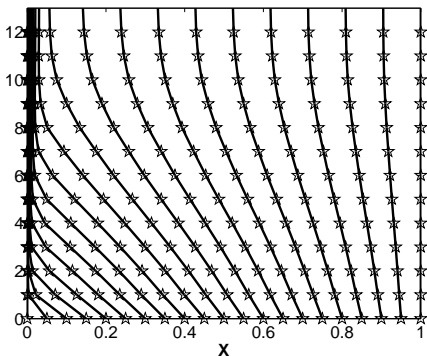


# Movement of the mesh towards left

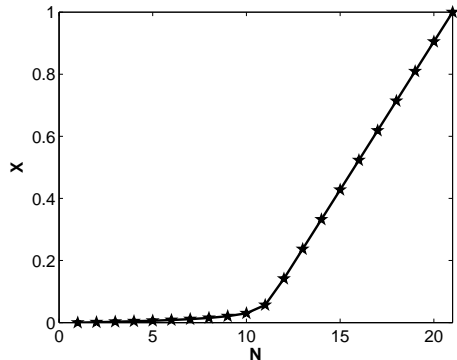


# Movement of the mesh towards left

$$\begin{cases} -\varepsilon u''_{\varepsilon}(x) - u'_{\varepsilon}(x) = 0, & x \in (0, 1), \\ u_{\varepsilon}(0) = 1, & u_{\varepsilon}(1) = 0, \end{cases}$$



(a) Mesh movement toward left.



(b) Final computed mesh.

Figure: for  $\varepsilon = 10^{-2}$  and  $N = 20$ .



# Model problem

Consider the following singularly perturbed Parameterized BVP:

$$\begin{cases} Lu(x) \equiv \varepsilon u'(x) + f(x, u, \lambda) = 0, & x \in \Omega = (0, 1), \\ u(0) = s_0, \quad u(1) = s_1, \end{cases} \quad (5)$$



# Model problem

Consider the following singularly perturbed Parameterized BVP:

$$\begin{cases} Lu(x) \equiv \varepsilon u'(x) + f(x, u, \lambda) = 0, & x \in \Omega = (0, 1), \\ u(0) = s_0, & u(1) = s_1, \end{cases} \quad (5)$$

- $0 < \varepsilon \ll 1$  is a small parameter.  $\lambda =$  Control parameter.



# Model problem

Consider the following singularly perturbed Parameterized BVP:

$$\begin{cases} Lu(x) \equiv \varepsilon u'(x) + f(x, u, \lambda) = 0, & x \in \Omega = (0, 1), \\ u(0) = s_0, & u(1) = s_1, \end{cases} \quad (5)$$

- $0 < \varepsilon \ll 1$  is a small parameter.  $\lambda =$  **Control parameter**.
- The functions  $f(x, u, \lambda)$  is sufficiently smooth such that

$$\begin{cases} f(x, u, \lambda) \in C^3([0, 1 \times \mathbb{R}^2]), \\ 0 < \alpha \leq \frac{\partial f}{\partial u} \leq \alpha^* < \infty & (x, u, \lambda) \in [0, 1] \times \mathbb{R}^2, \\ 0 < m \leq \left| \frac{\partial f}{\partial \lambda} \right| \leq M < \infty & (x, u, \lambda) \in [0, 1] \times \mathbb{R}^2. \end{cases} \quad (6)$$

- $s_0, s_1$  are given constants.



# Model problem

Consider the following singularly perturbed Parameterized BVP:

$$\begin{cases} Lu(x) \equiv \varepsilon u'(x) + f(x, u, \lambda) = 0, & x \in \Omega = (0, 1), \\ u(0) = s_0, \quad u(1) = s_1, \end{cases} \quad (5)$$

- $0 < \varepsilon \ll 1$  is a small parameter.  $\lambda = \text{Control parameter}$ .
- The functions  $f(x, u, \lambda)$  is sufficiently smooth such that

$$\begin{cases} f(x, u, \lambda) \in C^3([0, 1 \times \mathbb{R}^2]), \\ 0 < \alpha \leq \frac{\partial f}{\partial u} \leq \alpha^* < \infty & (x, u, \lambda) \in [0, 1] \times \mathbb{R}^2, \\ 0 < m \leq \left| \frac{\partial f}{\partial \lambda} \right| \leq M < \infty & (x, u, \lambda) \in [0, 1] \times \mathbb{R}^2. \end{cases} \quad (6)$$

- $s_0, s_1$  are given constants.
- The solution  $u(x)$  exhibits a **boundary layer** of width  $\mathcal{O}(\varepsilon)$  at  $x = 0$ .

# A brief background

- **Amiraliyev et. al. (2006)** solved the BVP (5) using upwind scheme on shishkin mesh and shown the order of convergence *i.e.*,  $\mathcal{O}(N^{-1} \ln N)$ .



# A brief background

- **Amiraliyev et. al. (2006)** solved the BVP (5) using upwind scheme on shishkin mesh and shown the order of convergence *i.e.*,  $\mathcal{O}(N^{-1} \ln N)$ .
- **Z. Cen (2008)** solved the BVP (5) using hybrid scheme on shishkin mesh.





# A brief background

- **Amiraliyev et. al. (2006)** solved the BVP (5) using upwind scheme on shishkin mesh and shown the order of convergence *i.e.*,  $\mathcal{O}(N^{-1} \ln N)$ .
- **Z. Cen (2008)** solved the BVP (5) using hybrid scheme on shishkin mesh.
- **F. Xie et. al. (2008)** used boundary layer correction technique to solved the BVP (5).



# A brief background

- **Amiraliyev et. al. (2006)** solved the BVP (5) using upwind scheme on shishkin mesh and shown the order of convergence *i.e.*,  $\mathcal{O}(N^{-1} \ln N)$ .
- **Z. Cen (2008)** solved the BVP (5) using hybrid scheme on shishkin mesh.
- **F. Xie et. al. (2008)** used boundary layer correction technique to solved the BVP (5).
- **Whether the adaptive grid approach can be applied to the BVP (5)?**



# A brief background

- **Amiraliyev et. al. (2006)** solved the BVP (5) using upwind scheme on shishkin mesh and shown the order of convergence *i.e.*,  $\mathcal{O}(N^{-1} \ln N)$ .
- **Z. Cen (2008)** solved the BVP (5) using hybrid scheme on shishkin mesh.
- **F. Xie et. al. (2008)** used boundary layer correction technique to solved the BVP (5).
- **Whether the adaptive grid approach can be applied to the BVP (5)?**
- **Whether we can get more efficient and accurate  $\varepsilon$ -uniform method using the adaptive grid for the BVP (5) ?**



# Discrete problem

The upwind finite difference scheme for (5) takes the form

$$\begin{cases} L^N U_j \equiv -\varepsilon D^- U_j + f(x_j, U_j, \lambda^n) = 0, & 1 \leq j \leq N-1, \\ U_0 = s_0, \quad U_N = s_1. \end{cases} \quad (7)$$

where  $D^- U_j = \frac{U_j - U_{j-1}}{h_j}$ ,



# Discrete problem

The upwind finite difference scheme for (5) takes the form

$$\begin{cases} L^N U_j \equiv -\varepsilon D^- U_j + f(x_j, U_j, \lambda^n) = 0, & 1 \leq j \leq N-1, \\ U_0 = s_0, \quad U_N = s_1. \end{cases} \quad (7)$$

where  $D^- U_j = \frac{U_j - U_{j-1}}{h_j}$ ,

## Lemma

*The solution  $\{u(x), \lambda\}$  of (5) satisfies the following inequalities:*

$$|\lambda| \leq C, \quad |u^k(x)| \leq C \left\{ 1 + \varepsilon^{-k} \exp\left(-\frac{\alpha x}{\varepsilon}\right) \right\}, \quad x \in \overline{\Omega}, \quad k = 0, 1, 2, 3$$



# Main Result

We solve the nonlinear problem (7) using the following iteration technique:

$$\lambda^n = \lambda^{n-1} - \frac{(s_1 - u_{N-1}^{n-1})\rho_N^{-1} + f(1, s_1, \lambda^{n-1})}{\partial f / \partial \lambda(1, s_1, \lambda^{n-1})},$$

$$u_i^n = u_i^{n-1} - \frac{(u_i^{n-1} - u_{i-1}^n)\rho_i^{-1} + f(x_i, u_i^{n-1}, \lambda^n)}{\partial f / \partial u(x_i, u_i^{n-1}, \lambda^n) + \rho_i^{-1}},$$

where  $\rho_i = h_i/\varepsilon$  and  $\lambda^{(0)}, u_i^{(0)}$  are the initial iterations given.



# Main Result

We solve the nonlinear problem (7) using the following iteration technique:

$$\lambda^n = \lambda^{n-1} - \frac{(s_1 - u_{N-1}^{n-1})\rho_N^{-1} + f(1, s_1, \lambda^{n-1})}{\partial f / \partial \lambda(1, s_1, \lambda^{n-1})},$$

$$u_i^n = u_i^{n-1} - \frac{(u_i^{n-1} - u_{i-1}^n)\rho_i^{-1} + f(x_i, u_i^{n-1}, \lambda^n)}{\partial f / \partial u(x_i, u_i^{n-1}, \lambda^n) + \rho_i^{-1}},$$

where  $\rho_i = h_i/\varepsilon$  and  $\lambda^{(0)}, u_i^{(0)}$  are the initial iterations given.

## Theorem

*Let  $\{u(x), \lambda\}$  and  $\{U_j^N, \lambda^N\}$  be the exact solution and discrete solution on grids defined above respectively. Then, there exists a constant  $C$  independent of  $N$  and  $\varepsilon$  such that*

$$\max_j |u(x_j) - U_j^N| < CN^{-1}, \quad |\lambda - \lambda^N| < CN^{-1}. \quad (8)$$



# Numerical Example

## Example

$$\begin{cases} \varepsilon u'(x) + 2u - \exp(-u) + x^2 + \lambda + \tanh(\lambda + x) = 0, \\ x \in \Omega = (0, 1), \\ u(0) = 1, \quad u(1) = 0. \end{cases} \quad (9)$$





# Numerical Example

## Example

$$\begin{cases} \varepsilon u'(x) + 2u - \exp(-u) + x^2 + \lambda + \tanh(\lambda + x) = 0, \\ x \in \Omega = (0, 1), \\ u(0) = 1, \quad u(1) = 0. \end{cases} \quad (9)$$

- The exact solution is not available.



# Numerical Example

## Example

$$\begin{cases} \varepsilon u'(x) + 2u - \exp(-u) + x^2 + \lambda + \tanh(\lambda + x) = 0, \\ x \in \Omega = (0, 1), \\ u(0) = 1, \quad u(1) = 0. \end{cases} \quad (9)$$

- The exact solution is not available.
- The error is calculated by the idea of interpolation.



# Numerical Example

## Example

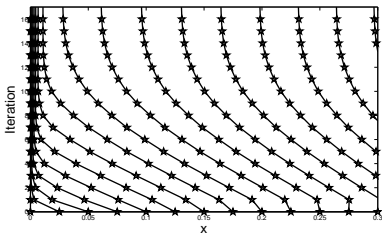
$$\begin{cases} \varepsilon u'(x) + 2u - \exp(-u) + x^2 + \lambda + \tanh(\lambda + x) = 0, \\ x \in \Omega = (0, 1), \\ u(0) = 1, \quad u(1) = 0. \end{cases} \quad (9)$$

- The exact solution is not available.
- The error is calculated by the idea of interpolation.
- Define

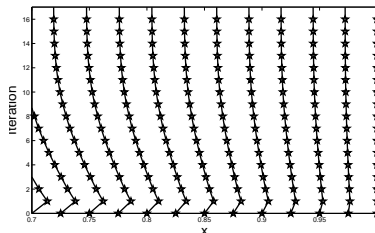
$$E_{\varepsilon,u}^N = \max_j |U_j^N - \bar{U}_j^{2N}|, \quad E_{\varepsilon,\lambda}^N = |\lambda^N - \bar{\lambda}^{2N}|$$

$$r_{\varepsilon,u}^N = \log_2 \left( \frac{E_{\varepsilon,u}^N}{E_{\varepsilon,u}^{2N}} \right), \quad r_{\varepsilon,\lambda}^N = \log_2 \left( \frac{E_{\varepsilon,\lambda}^N}{E_{\varepsilon,\lambda}^{2N}} \right).$$

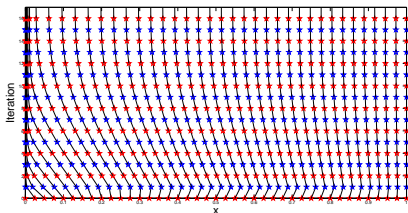
# Graphs



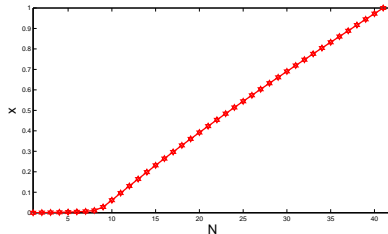
(a) Mesh movement in the layer region.



(b) Mesh movement in the regular region.



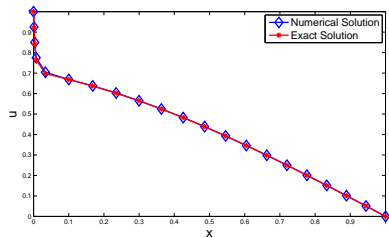
(a) Mesh movement.



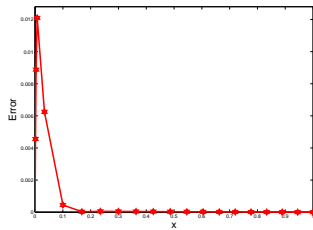
(b) Final computed mesh.

Figure: Mesh movement for  $\varepsilon = 1e - 2$ , and  $N = 40$ .

# Graphs and Tables



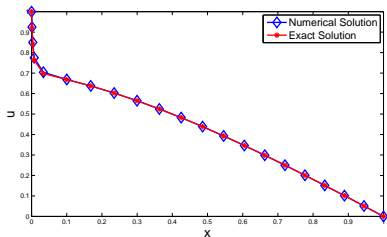
(a) Solutions.



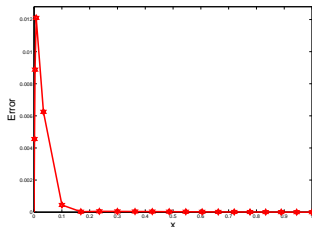
(b) Error.

Figure: Solutions and the error for  $\varepsilon = 1e - 2$ , and  $N = 20$ .

# Graphs and Tables



(a) Solutions.



(b) Error.

Figure: Solutions and the error for  $\varepsilon = 1e - 2$ , and  $N = 20$ .

Table: Maximum point-wise errors  $E_{\varepsilon, u}^N$  and the rate of convergence  $r_{\varepsilon, u}^N$ .

$\varepsilon$	Number of intervals $N$						
	16	32	64	128	256	512	1024
$1e - 4$	1.369e-02 0.67	8.567e-03 0.85	4.763e-03 0.91	2.537e-03 0.93	1.336e-03 0.95	6.903e-04 0.97	3.526e-04
$1e - 8$	1.3705e-2 0.68	8.5717e-3 0.85	4.7648e-3 0.91	2.5386e-3 0.92	1.337e-03 0.95	6.910e-04 0.97	3.532e-04



# Maximum point-wise Error with rate of convergence

Table: Maximum point-wise errors  $E_{\varepsilon,\lambda}^N$  and the rate of convergence  $r_{\varepsilon,\lambda}^N$ .

$\varepsilon$	Number of intervals $N$						
	16	32	64	128	256	512	1024
$1e-4$	1.548e-07 1.10	7.206e-08 1.07	3.427e-08 1.21	1.478e-08 1.09	6.936e-9 1.06	3.335e-09 1.17	1.482e-09
$1e-8$	1.549e-11 1.10	7.220e-12 1.05	3.485e-12 1.02	1.713e-12 1.01	8.501e-13 1.00	4.231e-13 1.05	2.051e-13



# Maximum point-wise Error with rate of convergence

Table: Maximum point-wise errors  $E_{\varepsilon,\lambda}^N$  and the rate of convergence  $r_{\varepsilon,\lambda}^N$ .

$\varepsilon$	Number of intervals $N$						
	16	32	64	128	256	512	1024
$1e-4$	1.548e-07 1.10	7.206e-08 1.07	3.427e-08 1.21	1.478e-08 1.09	6.936e-9 1.06	3.335e-09 1.17	1.482e-09
$1e-8$	1.549e-11 1.10	7.220e-12 1.05	3.485e-12 1.02	1.713e-12 1.01	8.501e-13 1.00	4.231e-13 1.05	2.051e-13

Table: Comparison of numerical results.

N		$\varepsilon = 1e-4$		$\varepsilon = 1e-6$	
		Result in Amiraliyev(2006)	Our result	Result in Amiraliyev(2006)	Our result
16	$E_{\varepsilon,\lambda}^N$	3.550e-06	1.548e-07	6.000e-08	1.549e-09
	$r_{\varepsilon,\lambda}^N$	1.01	1.10	1.00	1.10
32	$E_{\varepsilon,\lambda}^N$	1.760e-06	7.206e-08	3.000e-08	7.220e-10
	$r_{\varepsilon,\lambda}^N$	1.01	1.07	1.00	1.05





# Extension to the mixed kind BVP

## Example

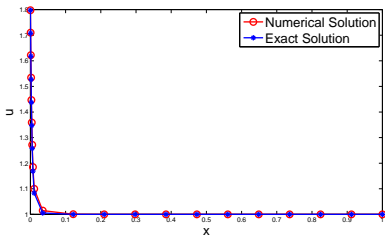
$$\begin{cases} \varepsilon u'(x) + 2u(x) - \exp(-u(x)) + \lambda = 0, & x \in \Omega = (0, 1), \\ u(0) + \varepsilon u'(0) = 1, & u(1) = 0. \end{cases} \quad (10)$$



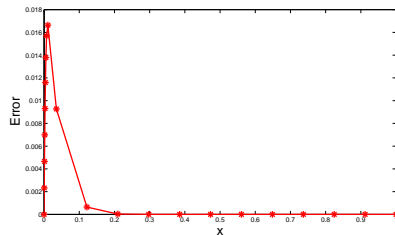
# Extension to the mixed kind BVP

## Example

$$\begin{cases} \varepsilon u'(x) + 2u(x) - \exp(-u(x)) + \lambda = 0, & x \in \Omega = (0, 1), \\ u(0) + \varepsilon u'(0) = 1, & u(1) = 0. \end{cases} \quad (10)$$



(a) Solution.



(b) Error.

Figure: Solution and the error for  $\varepsilon = 1e - 2$  and  $N = 20$ .



# Maximum point-wise Error and rate of convergence

**Table:** Maximum point-wise errors  $E_{\varepsilon,u}^N$  and rate of convergence  $r_{\varepsilon,u}^N$ .

$\varepsilon$	Number of intervals $N$						
	16	32	64	128	256	512	1024
$1e-4$	2.059e-02	1.132e-02	5.995e-03	3.153e-03	1.622e-03	8.313e-04	4.238e-04
	0.86	0.92	0.93	0.95	0.96	0.97	
$1e-8$	2.059e-02	1.132e-02	5.997e-03	3.157e-03	1.625e-03	8.317e-04	4.243e-04
	0.86	0.92	0.93	0.95	0.96	0.9703	



# Maximum point-wise Error and rate of convergence

Table: Maximum point-wise errors  $E_{\varepsilon,u}^N$  and rate of convergence  $r_{\varepsilon,u}^N$ .

$\varepsilon$	Number of intervals $N$						
	16	32	64	128	256	512	1024
$1e-4$	2.059e-02	1.132e-02	5.995e-03	3.153e-03	1.622e-03	8.313e-04	4.238e-04
	0.86	0.92	0.93	0.95	0.96	0.97	
$1e-8$	2.059e-02	1.132e-02	5.997e-03	3.157e-03	1.625e-03	8.317e-04	4.243e-04
	0.86	0.92	0.93	0.95	0.96	0.9703	

Table: Comparison of numerical results.

$\varepsilon$		$N = 64$		$N = 128$	
		Shishkin mesh	Adaptive grid	Shishkin mesh	Adaptive grid
$1e-4$	$E_{\varepsilon,u}^N$	9.858e-03	5.995e-03	5.956e-03	3.153e-03
	$r_{\varepsilon,u}^N$	0.7271	0.9272	0.7763	0.9587
$1e-6$	$E_{\varepsilon,u}^N$	9.858e-03	5.997e-03	5.956e-03	3.158e-03
	$r_{\varepsilon,u}^N$	0.7271	0.9249	0.7763	0.9610



# Conclusion



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.
- Optimal order *i.e.*,  $\mathcal{O}(N^{-1})$  is obtained.





# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.
- Optimal order *i.e.*,  $\mathcal{O}(N^{-1})$  is obtained.
- The proposed method is extended to mixed kind BVP.



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.
- Optimal order *i.e.*,  $\mathcal{O}(N^{-1})$  is obtained.
- The proposed method is extended to mixed kind BVP.

## Acknowledgments:



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.
- Optimal order *i.e.*,  $\mathcal{O}(N^{-1})$  is obtained.
- The proposed method is extended to mixed kind BVP.

## Acknowledgments:

- Thanks to my co-author: Mr. Deepti Shakti



# Conclusion

- A uniformly convergent upwind scheme is analyzed for singularly perturbed parameterized BVP exhibiting boundary layers using adaptive grid.
- It is shown that the bound obtained on the adaptive grid is in fact more accurate than that obtained on the Shishkin mesh.
- Optimal order *i.e.*,  $\mathcal{O}(N^{-1})$  is obtained.
- The proposed method is extended to mixed kind BVP.

## Acknowledgments:

- Thanks to my co-author: Mr. Deepti Shakti
- DST, Govt. of India for supporting under research grant no. SERB/F/7053/2013-14.



# References



G.M. Amiraliyev and H. Duru.

A note on parametrized singular perturbation problem.

*J. Comput. Appl. Math.*, **182**:233-242, 2005.



Z.Cen.

A second-order difference scheme for a parameterized singular perturbation problem.

*J. Comput. Appl. Math.*, **221**:174-182, 2008.



P.A. Farrell, A.F. Hegarty, J.J.H. Miller, E. O'Riordan, and G.I. Shishkin.

*Robust Computational Techniques for Boundary Layers.*

Chapman & Hall/CRC Press, Boca Raton, FL, 2000.



N. Kopteva and M. Stynes.

A robust adaptive method for a quasi-linear one dimensional convection-diffusion problem.

*SIAM J. Numer. Anal.*, **39**(4):1446–1467, 2001.



J.J.H. Miller, E. O'Riordan, and G.I. Shishkin.

*Fitted Numerical Methods for Singular Perturbation Problems.*

(revised edition), World Scientific, Singapore, 2012.



J. Mohapatra and S. Natesan.

Parameter-uniform numerical method for global solution and global normalized flux of singularly perturbed boundary value problems using grid equidistribution.

*Comput. Math. Appl.*, **60**(7):1924–1939, 2010.

# References



T.Pomentale.

A constructive theorem of existence and uniqueness for problem

$$y' = f(x, y, \lambda), \quad y(a) = \alpha, \quad y(b) = \beta.$$

Z. Angrew. Math. Mech., **56**(8):387-388, 1976.



M. Ronto, T. Csikos-Marinets.

On the investigation of some non-linear boundary value problems with parameter.

Math. Notes, Miscolc., **1**:157-166, 2000.



D. Shakti and J. Mohapatra

Uniform numerical method for a class of parameterized singularly perturbed boundary value problems.

*submitted for publication.*



F. Xie, J. Wang, W. Zhang and M. He

A novel method for a class of parameterized singularly perturbed boundary value problems.

J. Comput. Appl. Math., **213**:258-267, 2008.



**Thank You.**

