

# Prediction Based Dynamic Load Balancing Techniques in Heterogeneous Clusters

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**Abstract-**The goal of load balancing is to assigns to each node a number of tasks proportional to its performance. Many load balancers have been proposed that deal with applications with homogeneous tasks but applications with heterogeneous tasks have proven to be far more complex to handle. In this paper we present a load balancing techniques that can deal with applications with heterogeneous cluster. Here we are considering three type of load I/O, CPU, MEMORY. For efficient load balancing we are proposed a new techniques that reduce the average response time .For that we are using the prediction scheme that predict the requirement of task and then according to prediction scheme this techniques assign the task to best suitable node.

**Keywords:** Heterogeneous cluster, I/O intensive load, Load balancing

## I. INTRODUCTION

Load balancing (LB) is a critical issue in parallel and distributed systems for the efficient utilization of the computational resources. There is a large body of literature on load balancing and all the proposed load balancing algorithms can be broadly characterized as static and dynamic. The focus of this paper is on the dynamic load balancing algorithms and the processing times of the jobs are known at the time of execution. Load balancing can be static or dynamic.

In static scheduling, the assignment of the tasks to the nodes is done before the execution of the program. Information regarding task execution time and processing resources is assumed to be known at compile time. A task is always executed on the node to which it is assigned.

Dynamic scheduling is based on the re-distribution of processes among the processors during execution time. This redistribution is performed by transferring tasks from heavily-loaded processors to lightly-loaded processors with an aim to minimize the processing time of the application. The advantage of dynamic load balancing over static scheduling is that the system need not be aware of run-time behavior of the application before execution. The flexibility inherent in dynamic load balancing allows for adaptation to unforeseen application requirements at run-time. The major disadvantage of dynamic load balancing schemes is the run-time overhead due to:

- [1] The load information transfer among processors,
- [2] The decision-making process for the selection of processes and processor for job transfers, and
- [3] The communication delay due to task relocation itself.

Dynamic LB algorithms can be further classified into a centralized approach and a decentralized approach. In the centralized approach only one node in the distributed system acts as the central controller. It has a global view of the load information in

the system, and decides how to allocate jobs to each of the nodes. The rest of the nodes act as slaves; they only execute the jobs assigned by the controller. The centralized approach is more beneficial when the communication cost is less significant, e.g. in the shared-memory multi-processor environment.

The main motivation of our study is to propose a centralized dynamic LB algorithm that can cater for the following unique characteristics of practical distributed Computing environment:

- Heterogeneous system: There may be a difference in the hardware architecture, operating systems, computing power and resource capacity among sites. In this study, heterogeneity only refers to the processing power of site.
- Effects from considerable communication delay: The communication overhead involved in capturing load information before making a dispatching decision can be a major issue negating the advantages of job migration. We should not ignore the considerable dynamic communication delay in disseminating load updates.

Most load balancers were designed to handle applications with homogeneous tasks, for example data parallel application or tree-based algorithms. A lot of applications however consist of heterogeneous tasks, i.e. tasks performing different operation or operating on different types of data. Due to uneven job arrival patterns and unequal computing capacities and capabilities, the computers in one node may be overloaded while others in a different node may be under-utilized. It is therefore desirable to dispatch jobs to idle or lightly loaded computers to achieve better resource utilization and reduce the average job response time.

The rest of the paper is organized as follows. In the section 2 that follows, related work in the literature is briefly reviewed. In section 3, we describe the system model. In section 4 we describe the novel load balancing algorithm. Finally concludes the paper by summarizing the main contribution of this paper.

## II. RELATED WORK

There are many approaches to balancing load in disk I/O resource can be found in literature [1][2][3][4][6][10]. Xiao Qin[1] proposed a algorithm IOLB and compare this algorithm with conventional CPU- and memory-aware load balancing schemes and shows that the IOLB algorithm significantly improves the resource utilization of a cluster under I/O-intensive workload.

Mais Nijim Tao Xie,2005 developed a performance model for self-manage computer systems under dynamic workload condition, where both CPU- and I/O-intensive applications are running in computer systems. They shows that the controller is capable of achieving high performance for computer systems under workloads exhibiting high variabilities.

Xiao Qin et al.[4] proposed a feedback control mechanism to improve the performance of a cluster by adaptively manipulating the I/O buffer sizes. The primary objective of this mechanism is to minimize the number of page faults for memory-intensive jobs while

improving the buffer utilization of I/O-intensive jobs. The feedback controller judiciously configures the weights to achieve an optimal performance. Meanwhile under a workload where the memory demand is high, the buffer sizes are decreased to allocate more memory for memory-intensive jobs, thereby leading to a low page-fault rate. Increasing attention has been drawn toward I/O-intensive application. Kandaswamy et al.[10] examined optimization techniques and architecture scalability. They evaluated the effect of the techniques using five I/O-intensive applications from both small and large applications domain.

Xiao Qin et al.[6] developed two effective I/O-aware load-balancing schemes, which make it possible to balance I/O load by assigning I/O-intensive sequential and parallel jobs to nodes with light I/O loads. However, the above techniques are insufficient for automatic computing platforms due to the lack of adaptability. We proposed an algorithm that takes all the parallel tasks and balances the I/O-intensive load with an effective manner.

### III. SYSTEM MODEL

In this study we have considered a cluster computing platform of a heterogeneous system in which a set of  $N = \{N_1, N_2, N_3, \dots, N_n\}$  nodes are connected via a high speed network. Each node in this model is composed of a combination of various resources including processor, memory, disk, network connectivity, and every node differs with its processor, memory, and disk. A load manager or master node is responsible for load balancing and monitoring available resources of the node. Fig 1 shows the queuing model for the load manager.

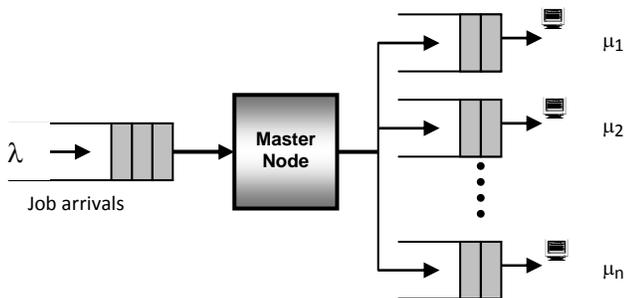


Fig. 1. Queuing model for load manager

The load manager or master node processes all arrival tasks in a FCFS manner. Here we are assuming that all tasks are to the load manager as a poison process. After being handled by the load manager, tasks are dispatched to one of the best-suited nodes for execution. The nodes, each of which contains a local queue, can execute tasks in parallel. The load manager is composed of three modules: (1) predictor; (2) selector; (3) scheduler;

When a new task arrives at the load manager, the identification of the program being executed is sent to the predictor, which predicts the resource requirements of the task. These predicted values are then fed to the selector, which selects the node with under-utilized and well-suited resources.

The predictor is used to predict the file I/O, CPU, and memory requirements of a task. For this, we use the prediction scheme described in [7], which uses a statistical pattern-recognition to predict the task requirements. The prediction is made at the beginning of a process's life, given the identity of the program being executed.

The prediction scheme consists of two parts. In the first part, which is an off-line procedure, resource usage states are determined for program executions of a given UNIX system. Resource usage data is collected for all processes that ran on the system for a few days; this data is analyzed as follows: Each process is represented by a point in a three-dimensional space, where each dimension corresponds to the resources of the system, i.e., the CPU, the memory, and the file I/O. A statistical clustering algorithm is then used to identify the high density regions of this three-dimensional space (i.e., determine the number of such regions and the means of their centroids). By definition, most program executions occur in or near these regions, and therefore they are referred to as the resource usage states.

In the second part, which is an on-line procedure, actual prediction is made. The prediction scheme builds and maintains a state-transition model for each program on an on-going basis. The states of the model are the resource usage states defined above. Suppose a program has been executed several times, providing a sequence of execution instances. First, the sequence of execution instances is converted into a sequence of resource usage states by assigning the nearest resource usage state to each execution instance. The state transition probabilities are then calculated from this new sequence to build a state-transition model for the program. The prediction is a weighted mean calculation of resource requirements using the program's current state-transition model and the actual resource usage in its most recent execution. See [7] for further details. Then the predicted value is fed to the selector, which is used to select the best node among all nodes where the task will execute. That node is under-loaded and gives a response effectively. The scheduler is responsible to dispatch the task to the node selected by the selector. Then the task will be sent to that node and will execute there. The load manager updates the load status table.

### IV. LOAD BALANCING ALGORITHM

We proposed an algorithm for a wide variety of workload conditions including I/O-intensive, CPU-intensive, and memory-intensive loads. The objective of the proposed algorithm is to balance the load of three types of resources across all nodes in a cluster. In this study, we analytically evaluate the performance of the algorithm; we are focused on a remote execution mechanism in which a task can be running on a remote node where it started execution. Thus, preemptive migrations of tasks are not supported in our algorithm.

To describe this algorithm, we first introduce the following three load indices with respect to I/O, CPU, and memory resources. (1) CPU load of a node is characterized by the length of the CPU waiting queue, denoted as  $L_{CPU}(i)$ , to identify whether node  $i$ 's CPU is overloaded. (2) Memory load of a node is the sum of the memory space allocated to all the tasks running on that node. The memory load of node  $i$  is denoted as  $L_{MEM}(i)$ . (3) I/O load measures two types of I/O accesses, i.e. (a) implicit I/O request includes page faults; (b) explicit I/O request issued from tasks. IO load index of node  $i$  is denoted as  $L_{IO}(i)$ . TABLE I shows the definition of notation used in this paper.

Now we describe the load balancing algorithm of which the pseudo code is shown in Fig. 2. Given a set of independent tasks submitted to the load manager, our algorithm makes an effort to balance the load of the cluster resources by allocating each task to a node such that the expected response time is minimized.

For each task  $t$ , our algorithm repeatedly performs steps 2-19 described as follows:

First, it will predict all three  $IOREQ_j$ ,  $CPUREQ_j$ ,  $MEMREQ_j$  requirements of task  $j$  from the set of tasks by step 2. These three predicted

value are important because according to this value task execute with best suited node. Step 3 is used to find the highest requirements of task and it is responsible for initiating the process of balancing I/O resources. Step 4-7 are used to balance the I/O load. In step 4 If the I/O requirements of task j are high then it will find the set of node where I/O load is minimum and satisfy all three requirements. Step 5 calculates the response time of task with all selected node. Step 6 if the response time is minimum with particular node then task will send to that specific node.

TABLE I  
DEFINITION OF NOTATION

Notation	Definition
N	Number of node in heterogeneous system
t	Task submitted to the system
$\lambda$	Arrival rate of task
$\mu_n$	Service rate of heterogeneous system
$IOREQ_j$	I/O requirement of task j
$CPUREQ_j$	CPU requirement of task j
$MEMREQ_j$	MEMORY requirement of task j
$L_a^{IO}$	I/O load on node(1≤a≤n)
$L_a^{CPU}$	CPU load on node(1≤a≤n)
$L_a^{MEM}$	MEMORY load on node(1≤a≤n)
$L_{IO}^k$	I/O load index on set of k node that satisfy all requirements
$L_{CPU}^k$	CPU load index on set of k node
$L_{MEM}^k$	MEMORY load index on set of k node
$R_j^k$	Response time of task on set of k nodes

Second, step 8 if the memory requirements of task are high then it will perform to step 9-12 to balance memory load among all nodes. Page fault behaviors occur when the memory space allocated by running tasks exceeds the amount of available memory. That's why it is necessary to balance memory to minimize the page fault. Step 9 searches the set of node with minimum memory load and

satisfies all three resource requirement of task. Step 10 calculate the response time of task with all selected node then step 11 find the minimum response time of task from selected node then step 12 dispatch the to selected node.

**Algorithm: Load balancing**

Input: a job with task j submitted to master node

1. for each task do
2. Predict the value of IO,CPU and memory requirements
3. if  $IOREQ_j = \max(IOREQ_j, CPUREQ_j, MEMREQ_j)$
4. choose set of k node such that node  $L_{IO}^k = \min_{a=1}^n(L_a^{IO})$  satisfy the all three requirements
5. calculate response time  $R_j^k$  of task j in set of k node
6. if  $R_j^i = \min_{b=1}^k(R_j^b)$  then
7. dispatch the task to node  $N_i$  and execute there
8. else if  $MEMREQ_j = \max(IOREQ_j, CPUREQ_j, MEMREQ_j)$
9. choose set of k node such that node  $L_{MEM}^k = \min_{a=1}^n(L_a^{MEM})$  satisfy the requirements
10. calculate response time  $R_j^k$  of task j in set of k node
11. if  $R_j^i = \min_{b=1}^k(R_j^b)$  then
12. dispatch the task to node  $N_i$  and execute there
13. else if  $CPUREQ_j = \max(IOREQ_j, CPUREQ_j, MEMREQ_j)$
14. choose set of k node such that node  $L_{CPU}^k = \min_{a=1}^n(L_a^{CPU})$  satisfy the requirements
15. calculate response time  $R_j^k$  of task j in set of k node
16. if  $R_j^i = \min_{b=1}^k(R_j^b)$  then
17. dispatch the task to node  $N_i$  and execute there
18. update the load status;
19. end for

Fig. 2 .Pseudo code of the IO load balancing algorithm

Third, step 13 is responsible if the CPU requirements of task is high and step 14 is search the set node with minimum CPU load among all node that satisfy all requirements of task. And then calculate the response time of task in each selected node. Step16 find node that gives minimum response time to execute the task. Step 17 dispatches the task to the selected node. Last step 21 maintains updated load information that is send to the load manger

CONCLUSION

Even though there are number of different dynamic load balancing techniques for cluster systems, their efficiency depends topology of the communication network that connects nodes. This research has developed an efficient load balancing for I/O, CPU, MEMORY intensive for this we develop a new way to predict and calculate the load of cluster nodes. The proposed load balancing

scheme aim to achieve the effective usage of global disk resources in cluster. This can minimize the average slow down of all parallel jobs running on a cluster and reduce the average response time of the jobs.

Future studies can be performed in following direction. First, we will evaluate the performance of scheme on a large scale of cluster. Second, we have assumed the task is independent, so we will also simulate this scheme for inter-dependent task. Third, in this study we have assumed network communication cost is negligible, therefore we will extend this to balance load in network resource.

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