PARAMETRIC INSTABILITY OF DOUBLY CURVED PANELS SUBJECTED TO NON-UNIFORM HARMONIC LOADING

S. K. Sahu and P. K. Datta

Department of Aerospace Engineering, I.I.T., Kharagpur-721302, India

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Full address of person to whom proofs should be sent

Professor P.K. Datta

Department of Aerospace Engineering

Indian Institute of Technology, Kharagpur

At/P.O. Kharagpur-721302(W.B.)India

e-mail pkdatta@aero.iitkgp.ernet.in

Summary

The parametric instability characteristics of doubly curved panels subjected to various in-plane static and periodic compressive edge loadings, including partial and concentrated edge loadings are studied using finite element analysis. The first order shear deformation theory is used to model the doubly curved panels, considering the effects of transverse shear deformation and rotary inertia. The theory used is the extension of dynamic, shear deformable theory according to the Sander's first approximation for doubly curved shells, which can be reduced to Love's and Donnell's theories by means of tracers. The effects of static load factor, aspect ratio, radius to thickness ratio, shallowness ratio, boundary conditions and the load parameters on the principal instability regions of doubly curved panels are studied in detail using Bolotin's method. Quantitative results are presented to show the effects of shell geometry and load parameters on the stability boundaries. Results for plates and cylindrical shells are also presented as special cases and are compared with those available in the literature.

1. INTRODUCTION

Structural elements subjected to in-plane periodic forces may lead to parametric resonance, due to certain combinations of the values of load parameters. The instability may occur below the critical load of the structure under compressive loads over a range or ranges of excitation frequencies. Several means of combating resonance such as damping and vibration isolation may be inadequate and sometimes dangerous with reverse results [1]. Thus the parametric resonance characteristics are of great technical importance for understanding the dynamic systems under periodic loads. The dynamic instability characteristics of plates subjected to uniform loads were studied by Hutt and Salam [2] using Finite Element Method. Parametric resonance in shell structures under periodic loads had been of considerable interest since the subject was studied by Bolotin [3], Yao [4], Bieniek et al. [5] and Vijayaraghavan & Evan-Iwanowski [6]. The method of solution of these class of problems were to first reduce the equations of motion to a system of Mathieu-Hill equations and the parametric resonance characteristics were studied by different methods. A detailed study of resonances had carried out by Koval [7] using Donnel's shell theory. The stability of the steady state response of simply-supported circular cylinders subjected to harmonic excitation was investigated by Radwin and Genin [8] using variational equations. The parametric instability characteristics of circular cylindrical shells under static and periodic loading were studied by Nagai and Yamaki [9] using Galerkin procedure and Hsu's method. The dynamic stability and non-linear parametric vibration of isotropic cylindrical shells with added mass were considered by Kovtunov [10]. The dynamic instability of composite simply-supported circular cylindrical shell was analysed by the Method of Multiple Scale(MMS) by Cederbaum [11]. A perturbation technique was employed by Argento and Scott [12] to study the instability regions subjected to axial loading. The effects of static load and static snap through buckling on the instability for spherical and conical shells were investigated [13]using Galerkin method. The dynamic instability of conical shells are studied by Tani [14] using Finite Difference method and by Ng et al. [15] using Generalized Differential Quadrature method. The parametric resonance of a rotating cylindrical shell subjected to periodic axial loads is investigated by Ng et al. [16]. The parametric resonance of cylindrical shells under combined static and periodic loading was studied using different thin shell theories by Lam and Ng [17,18]. Most of the investigators studied the dynamic stability of uniformly loaded closed cylindrical shells with a simply supported boundary condition, using analytical approach.

The practical importance of stability analysis of doubly curved panels/open shells has been increased in structural, aerospace (skin panels in wings, fuselage etc.), submarine hulls and mechanical applications but this type of open shells/panels have received less attention because of complexities involved. The free vibration of doubly curved shallow shells/curved panels was studied by a number of researchers [19-22] and well reviewed [23,24]. Recently the vibration under uniform initial stress and buckling stresses were studied for thick simply-supported doubly curved open shells/panels through Hamilton's principle [25]. The buckling characteristics of isotropic flat panel [26, 27] and closed cylindrical shell [28, 29] due to concentrated loadings were also investigated. The study of the parametric instability behaviour of curved panels is new. Recently the dynamic stability of uniformly loaded cylindrical panels with transverse shear effects is studied by Ng, Lam and Reddy [30]. Besides this, the applied load is seldom uniform and the boundary condition may be completely arbitrary in practice. The application of non-uniform loading and general boundary conditions on the structural component will alter the global quantities such as free vibration frequency, buckling load and dynamic instability region(DIR).

In the present study, the parametric instability of doubly curved panels subjected to various in-plane uniform and non-uniform, including partial and concentrated edge loadings are investigated. The influences of various parameters like effects of static & dynamic load factors, aspect ratio, radius to side ratio, thickness, various boundary conditions, percentage of loaded length and position of concentrated loads on the instability behaviour of curved panels have been examined. The present formulation of the problem is made general to accommodate a doubly curved panel with finite curvatures in both the directions having arbitrary load and boundary conditions.

2. THEORY AND FORMULATIONS

The basic configuration of the problem considered here is a doubly curved panel as shown

in Figure 1, subjected to various non-uniform harmonic in-plane edge loadings.

2.1 GOVERNING EQUATIONS

The equation of equilibrium for free vibration of a shear deformable doubly curved panel subjected to in-plane external loading can be written as:

$$\frac{\partial N_1}{\partial x} + \frac{\partial N_6}{\partial y} + \frac{1}{2}C_2\left(\frac{1}{R_y} - \frac{1}{R_x}\right)\frac{\partial M_6}{\partial y} + C_1\frac{Q_1}{R_x} = \rho h\frac{\partial^2 u}{\partial t^2} + \frac{\rho h^3}{12R_y}\frac{\partial^2 \theta_x}{\partial t^2} \tag{1}$$

$$\frac{\partial N_6}{\partial x} + \frac{\partial N_2}{\partial y} - \frac{1}{2}C_2\left(\frac{1}{R_y} - \frac{1}{R_x}\right)\frac{\partial M_6}{\partial x} + C_1\frac{Q_2}{R_y} = \rho h\frac{\partial^2 v}{\partial t^2} + \frac{\rho h^3}{12R_y}\frac{\partial^2 \theta_y}{\partial t^2} \\
\frac{\partial Q_1}{\partial x} + \frac{\partial Q_2}{\partial y} - \frac{N_1}{R_x} - \frac{N_2}{R_y} + N_1^0\frac{\partial^2 w}{\partial x^2} + N_2^0\frac{\partial^2 w}{\partial x^2} = \rho h\frac{\partial^2 w}{\partial t^2} \\
\frac{\partial M_1}{\partial x} + \frac{\partial M_6}{\partial y} - Q_1 = \frac{\rho h^3}{12}\frac{\partial^2 \theta_x}{\partial t^2} + \frac{\rho h^3}{12R_y}\frac{\partial^2 u}{\partial t^2} \\
\frac{\partial M_6}{\partial x} + \frac{\partial M_2}{\partial y} - Q_2 = \frac{\rho h^3}{12}\frac{\partial^2 \theta_y}{\partial t^2} + \frac{\rho h^3}{12R_y}\frac{\partial^2 u}{\partial t^2}$$

where N_1^0 and N_2^0 are the external loading in X and Y directions respectively. C_1 and C_2 are tracers by which the analysis can be reduced to that of Sander's, Love's and Donnell's theories. The equation of motion can be written in matrix form as:

$$[M]\{\ddot{q}\} + [[K_e] - P[K_g]]\{q\} = 0$$
⁽²⁾

The in-plane load P(t) is periodic and can be expressed in the form

$$P(t) = P_s + P_t \cos\Omega t \tag{3}$$

where P_s is the static portion of P. P_t is the amplitude of the dynamic portion of P and Ω is the frequency of excitation. The static buckling load of elastic shell P_{cr} is the measure of the magnitudes of P_s and P_t ,

$$P_s = \alpha P_{cr}, \qquad P_t = \beta P_{cr} \qquad (4)$$

where α and β are termed as static and dynamic load factors respectively. Using Equation (3), the equation of motion is obtained as:

$$[M]\{\ddot{q}\} + [[K_e] - \alpha P_{cr}[K_g] - \beta P_{cr}[K_g] \cos\Omega t]\{q\} = 0$$

$$\tag{5}$$

Equation (5) represents a system of second order differential equations with periodic coefficients of the Mathieu-Hill type. The development of regions of instability arises from Floquet's theory which establishes the existence of periodic solutions. The boundaries of the dynamic instability regions are formed by the periodic solutions of period T and 2T, where $T = 2\pi/\Omega$. The boundaries of the primary instability regions with period 2T are of practical importance [3] and the solution can be achieved in the form of the trigonometric series

$$q(t) = \sum_{k=1,3,5}^{\infty} \left[\{a_k\} sin \frac{k\theta t}{2} + \{b_k\} cos \frac{k\theta t}{2} \right]$$

$$\tag{6}$$

Putting this in Equation (5) and if only first term of the series is considered, equating coefficients of $sin\frac{\theta t}{2}$ and $cos\frac{\theta t}{2}$ the equation becomes

$$\left[[K_e] - \alpha P_{cr}[K_g] \pm \frac{1}{2} \beta P_{cr}[K_g] - \frac{\Omega^2}{4} [M] \right] \{q\} = 0$$
(7)

Equation (7) represents an eigenvalue problem for known values of α , β and P_{cr} . The two conditions under a plus and minus sign correspond to two boundaries of the dynamic instability region. The eigenvalues are Ω , which give the boundary frequencies of the instability regions for given values of α and β . In this analysis, the computed static buckling load of the panel is considered as the reference load in line with Moorthy *et el.* [31] and Ganapathi *et al.* [32]. An eight-nodded curved isoparametric quadratic element is employed in the present analysis with five degrees of freedom u, v, w, θ_x and θ_y per node. First order shear deformation theory (FSDT) is used and the shear correction coefficient has been employed to account for the nonlinear distribution of the shear strains through the thickness. The displacement field assumes that mid-plane normal remains straight but not necessarily normal after deformation, so that

$$\bar{u}(x, y, z) = u(x, y) + z\theta_x(x, y)$$

$$\bar{v}(x, y, z) = v(x, y) + z\theta_y(x, y)$$

$$\bar{w}(x, y, z) = w(x, y)$$
(8)

where,

θ_x, θ_y are the rotations of the mid surface

Also $\bar{u}, \bar{v}, \bar{w}$ and u, v, w are the displacement components in the x, y, z directions at any section and at mid- surface respectively. The constitutive relationships for the shell are given by

$$F = [D]\{\varepsilon\} \tag{9}$$

where

$$F = [N_1, N_2, N_6, M_1, M_2, M_6, Q_1, Q_2]^T$$
(10)

$$[D] = \begin{bmatrix} \frac{Eh}{1-\nu^2} & \frac{\nu Eh}{1-\nu^2} & 0 & 0 & 0 & 0 & 0 & 0 \\ \frac{\nu Eh}{1-\nu^2} & \frac{Eh}{1-\nu^2} & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{Eh}{2(1+\nu)} & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{Eh^3}{12(1-\nu^2)} & \frac{\nu Eh^3}{12(1-\nu^2)} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{Eh^3\nu}{12(1-\nu^2)} & \frac{Eh^3}{12(1-\nu^2)} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{Eh^3}{24(1+\nu)} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & \frac{Eh}{2.4(1+\nu)} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \frac{Eh}{2.4(1+\nu)} \end{bmatrix}$$
(11)

A Reissner's shear correction factor of 5/6 is included for all numerical computations. Extension of shear deformable Sander's kinematic relations for doubly curved shells [33,34] are used in the analysis. The linear strain displacement relations are

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$$\varepsilon_{xl} = \frac{\partial u}{\partial x} + \frac{w}{R_x} + z\kappa_x$$
(12)

$$\varepsilon_{yl} = \frac{\partial v}{\partial y} + \frac{w}{R_y} + z\kappa_y$$

$$\gamma_{xyl} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + z\kappa_{xy}$$

$$\gamma_{yz} = \frac{\partial w}{\partial y} + \theta_y - C_1 \frac{v}{R_y}$$

$$\gamma_{xz} = \frac{\partial w}{\partial x} + \theta_x - C_1 \frac{u}{R_x}$$

where

$$\kappa_x = \frac{\partial \theta_x}{\partial x}, \\ \kappa_y = \frac{\partial \theta_y}{\partial y}$$
(13)
$$\kappa_{xy} = \frac{\partial \theta_y}{\partial y} + \frac{\partial \theta_y}{\partial x} + \frac{1}{2}C_2 \left(\frac{1}{R_y} - \frac{1}{R_x}\right) \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y}\right)$$

The element geometric stiffness matrix for the doubly curved panel is derived using the nonlinear strain components as:

$$\varepsilon_{xnl} = \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{w}{R_x} \right)^2 + \frac{1}{2} \left(\frac{\partial v}{\partial x} \right)^2 + \frac{1}{2} \left(\frac{\partial w}{\partial x} - \frac{u}{R_x} \right)^2 + \frac{1}{2} z^2 \left[\left(\frac{\partial \theta_x}{\partial x} \right)^2 + \left(\frac{\partial \theta_y}{\partial x} \right)^2 \right]$$
(14)

$$\varepsilon_{ynl} = \frac{1}{2} \left(\frac{\partial u}{\partial y} \right)^2 + \frac{1}{2} \left(\frac{\partial v}{\partial y} + \frac{w}{R_y} \right)^2 + \frac{1}{2} \left(\frac{\partial w}{\partial y} - \frac{v}{R_y} \right)^2 + \frac{1}{2} z^2 \left[\left(\frac{\partial \theta_x}{\partial y} \right)^2 + \left(\frac{\partial \theta_y}{\partial y} \right)^2 \right]$$
(14)

$$\gamma_{xynl} = \left[\left(\frac{\partial u}{\partial x} + \frac{w}{R_x} \right) \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \left(\frac{\partial v}{\partial y} + \frac{w}{R_y} \right) + \left(\frac{\partial w}{\partial x} - \frac{u}{R_x} \right) \left(\frac{\partial w}{\partial y} - \frac{v}{R_y} \right) \right]$$
$$+ z^2 \left[\left(\frac{\partial \theta_x}{\partial x} \right) \left(\frac{\partial \theta_x}{\partial y} \right) + \left(\frac{\partial \theta_y}{\partial x} \right) \left(\frac{\partial \theta_y}{\partial y} \right) \right]$$

The element matrices are derived as:

Elastic stiffness matrix

$$[K_e]_e = \int [B]^T [D] [B] dx dy \tag{15}$$

Geometric stiffness matrix

$$[K_{\sigma}]_e = \int [B_g]^T [\bar{\sigma}] [B_g] dx dy$$
(16)

Consistent mass matrix

$$[M]_e = \int [N]^T [I] [N] dx dy \tag{17}$$

The overall matrices $[K_e], [K_{\sigma}]$ and [M] are obtained by assembling the corresponding element matrices.

2.2 COMPUTER PROGRAM

A computer program has been developed to perform all the necessary computations. Element elastic stiffness matrices and mass matrices are obtained using a standard procedure. The geometric stiffness matrix is essentially a function of the in-plane stress distribution in the element due to applied edge loadings. Since the stress field is non-uniform, plane stress analysis is carried out using the Finite element method to determine the stresses and these are used to formulate the geometric stiffness matrix. Reduced integration technique is adopted in order to avoid possible shear locking. Element matrices are assembled into global matrices, using skyline technique. Subspace iteration method is adopted throughout to solve the eigenvalue problems.

3. RESULTS AND DISCUSSIONS

The convergence studies have been carried out for fundamental frequencies of vibration of cantilevered doubly-curved shells/panels for three different cases and the results are compared with Leissa *et al.* [20] in Table 1. From the above convergence study, 10×10 mesh has been employed to idealise the panel in the subsequent analysis. This idealisation is chosen in order to apply compression to a small fraction of the edge length and also for convergence criterion. To validate the formulation further, the free vibration frequency and critical buckling load for simply-supported uniformly loaded shells/panels, are compared with the literature [25] in Table 2. The above studies indicate good agreement between the present study and those from the literature. Once the free vibration and buckling results are validated, the dynamic instability studies are made.

3.1 PARAMETRIC INSTABILITY STUDIES

The parametric instability regions are plotted for a uniaxially loaded doubly curved panel with/without static component to consider the effects of static load factor, aspect ratio, boundary conditions, radius to thickness ratio, shallowness ratio, load band width and positions of concentrated edge loading. A simply supported doubly curved panel of dimensions $a = b = 400mm, h = 4mm, E = 0.7e11N/m^2, \nu = 0.3, \rho = 2800kg/m^3, R_x =$ $R_y = 2000mm$ is described as a standard case and the computed buckling load of this panel is taken as the reference load in line with Moorthy et *el.* [31].The non-dimensional excitation frequency $\Omega = \bar{\Omega}a^2\sqrt{\rho h/D}$ is used throughout the dynamic instability stud-

ies (unless otherwise mentioned), where $\overline{\Omega}$ is the excitation frequency in radian/second, $D = \frac{Eh^3}{12(1-\nu^2)}$. The effect of static component of load for $\alpha = 0.0, 0.2, 0.4$ and 0.6 on the instability regions is shown in Figure 2. Due to increase of static component, the instability regions tend to shift to lower frequencies and become wider. Figure 3 shows the effect of aspect ratio on instability regions. It is observed that, the onset of dynamic stability occurs much later with decrease of the aspect ratio but with increasing width of instability regions. Figure 4 shows the influence of different boundaries (SSSS, SCSC, CCCC) on the principal instability regions. As expected, the instability occurs at a higher excitation frequency from simply supported to clamped edges due to the restraint at the edges. The width of the instability regions are also decreased with the increase of restraint at the edges. The effect of radius to thickness ratio on instability regions is shown in Figure 5. The onset of dynamic instability regions are observed to be increasing with decrease of R_y/h ratio. Figure 6 shows the effect of shallowness ratio on instability regions. As seen from the figure, the instability excitation frequency is higher for decrease of shallowness by decreasing R_x and R_y . Studies have also been made (Figure 7) for comparison of instability regions for different shell geometries. It is observed that the excitation frequency increases with introduction of curvatures from plate to doubly curved panel. However the hyperbolic paraboloid shows similar instability behaviour as that of a flat panel with no stiffness being added due to the curvature of the panel. Similar observations were also obtained by Leissa and Kadi^[19] on a study of vibration of shells. The study is then extended for biaxial loading on the parametric excitation behaviour of doubly curved panels. The results are presented in Table 3. It was observed that instability appears at lower excitation frequency with increasing dynamic instability region. The investigation is then extended for partial and concentrated edge loading from one end. The load parameter

of c/b=0 corresponds to concentrated loads at the two opposite edges. A double pair of partial & concentrated loading from both ends and other types of non-uniform loading are also studied. The curved panels under non-uniform loading behave differently to that of under uniform loading. The onset of dynamic stability occurs earlier with the increase of percentage of loaded edge length. Figure 8 shows that the instability occurs later for a small patch loading (c/b=0.2) as compared to a higher band width (c/b=0.8). This may be due to the constraint at the edges. Similarly, the instability also depends on the positions of concentrated loading (Figure 9). As observed, the instability occurs at lower excitation frequencies with increase of distance from the edges (c/b). The curved panel with a small patch of loading behaves in a similar manner to that of a panel subjected to a pair of concentrated loading near the edges and shows highest stiffness among all the loadings considered.

4. CONCLUSION

The results of the stability studies of the shells can be summarised as follows:

1. Due to static component, the instability regions tend to shift to lower frequencies with wide instability regions showing destabilizing effect on the dynamic stability behaviour of the curved panel.

2. The onset of instability occurs at higher excitation frequencies with lower R_y/h ratios.

3. The instability regions have been influenced due to restraint provided at the edges.

4. The onset of instability region appears earlier for rectangular panels with the increase in aspect ratio.

5. The instability regions start at higher frequencies with lower shallowness ratio.

6. The curved panels show more stiffness with addition of curvatures. But the hyperbolic paraboloid panels behave like a plate with no stiffness being added due to curvature of the shell.

7. The instability appears at lower excitation frequency with increasing dynamic instability region with biaxial loading.

8. The onset of instability occurs at higher excitation frequencies for small patch and concentrated loads near the edges but at lower frequencies for long band width and concentrated loads away from the edges.

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NOTATIONS

- a, b Dimensions of shell
- R_x, R_y Radii of curvatures
- c Percentage of loaded length/distance of concentrated load from edge
- E Young's modulus
- ν Poisson's ratio
- ρ Mass density
- G shear modulus
- [K] Stiffness matrix
- $[K_{\sigma}]$ Geometric stiffness matrix
- [M] Mass matrix
- $\{q\}$ Vector of generalized cordinates
- w Deflection of mid-plane of shell
- θ_x, θ_y Rotations about axes
- Ω, ω Frequency of forcing function and transverse vibration
- α, β Static and dynamic load factors
- P_{cr} Critical buckling load

Table 1 Convergence of non-dimensional fundamental frequencies without in-plane load of doubly curved shells/panels.

$a/b = 1, b/h = 100, b/R_y = 0.2, \nu = 0.3$						
Non dimensional frequency, $\omega = \bar{\omega}a^2 \sqrt{(\frac{\rho h}{D})}$						
Mesh Non-dimensional frequencies of shells						
Division	Cylindrical Spherical Hyperbolic parabole					
4×4	8.3837	6.6529	6.6072			
8×8	8.3679	6.5787	6.5015			
10×10	8.3653	6.5748	6.4969			
Leissa[20]	(8.3683)	(6.5854)	(6.5038)			

Names of authors: Sri S. K. Sahu

Prof. P. K. Datta

Table 2 Non-dimensional fundamental frequencies and buckling loads for the doublycurved shell/panel.

a/b	=	1.	ν	=	0	.3
00,0					~	• •

Non dimensional frequency, $\omega = \bar{\omega}h_{\sqrt{\left(\frac{D}{G}\right)}}, \lambda = \frac{N_{x}\sigma}{D}$							
a/h	a/R_x	b/R_y	Non-dimensional frequencies		Non-dimensional Buckling loads		
			Present FEM Matsunaga[25]		Present FEM	Matsunaga[25]	
10	0	0	0.09303	0.09315	36.8284	36.9242	
	0.2	0.2	0.09822	0.09826	41.0487	41.0872	
	0	0.2	0.09426	0.09436	37.8075	37.8904	
	-0.2	0.2	0.09264	0.09276	36.5235	36.6162	
20	0	0	0.02386	0.02387	38.7757	38.7945	
	0.2	0.2	0.02873	0.02872	56.2143	56.1620	
	0	0.2	0.02515	0.02515	43.0581	43.0670	
	-0.2	0.2	0.02373	0.02378	38.4618	38.5033	

 $a/b = 1, \nu = 0.3$ Non dimensional frequency, $\omega = \bar{\omega} h_{\star} \sqrt{(\underline{\rho})} \ \lambda = \frac{N_x b^2}{2}$

Names of authors: Sri S. K. Sahu

Prof. P. K. Datta

Table 3 Primary regions of instability for the doubly-curved panel subjected to different loading conditions .

 $a=b=400mm, h=4mm, E=0.7e11N/m^2, \nu=0.3, \rho=2800kg/m^3$

 $R_x = R_y = 2000mm, \alpha = 0.2$

Non dimensional frequency, $\Omega = \bar{\Omega} a^2 \sqrt{\rho h/D}$						
β	uniaxial loading		biaxial loading			
	U	L	U	L		
0	133.0780	133.0780	128.3204	128.3204		
0.2	135.3942	130.7208	133.0780	123.3793		
0.4	137.6714	128.3203	137.6714	118.2320		
0.6	139.9115	121.0582	142.1164	107.3603		
0.8	142.1164	110.2660	146.4265	91.6730		

Names of authors: Sri S. K. Sahu

Prof. P. K. Datta

Prof. P. K. Datta



Prof. P. K. Datta



Figure 3 Effect of aspect ratio on instability region of the curved panel for a/b= 1, 2 and 3, $a/R_x = 0, b/R_y = 0.2, \alpha = 0.2$



Figure 4 Effect of boundary conditions (SSSS, CSCS, CCCC) on instability region of the curved panel for a/b=1, $a/R_x=0.0, b/R_y=0.2$ and $\alpha=0.2$



Prof. P. K. Datta



Prof. P. K. Datta



Prof. P. K. Datta



Prof. P. K. Datta



Prof. P. K. Datta

Figure 1 Geometry and co-ordinate systems of a doubly curved panel

Figure 2 Effect of static load factor on instability region of a fully loaded curved panel:

a/b=1,
$$a/R_x = 0.2, b/R_y = 0.2$$
, for $\alpha = 0.0, 0.2, 0.4, 0.8$

Figure 3 Effect of aspect ratio on instability region of the curved panel for a/b=1, 2 and

3,
$$a/R_x = 0, b/R_y = 0.2, \alpha = 0.2$$

Figure 4 Effect of boundary conditions (SSSS, SCSC, CCCC) on instability region of the curved panel for a/b=1, $a/R_x = 0.0$, $b/R_y = 0.2$ and $\alpha = 0.2$

Figure 5 Effect of thickness on instability region of the curved panel for a/b=1, $R_x/h = R_y/h = 625,500,375$ and $\alpha = 0.2$

Figure 6 Effect of R_y/b on instability region of the curved panel for a/b=1, $R_x/a = R_y/b = 3, 5, 10, \alpha = 0.2$

Figure 7 Effect of curvature on instability region of different curved panels for a/b=1, flat panel $(a/R_x = b/R_y = 0)$, Cylindrical $(a/R_x = 0, b/R_y = 0.2)$, Spherical $(a/R_x = b/R_y = 0.2)$, Hyperbolic paraboloid $(a/R_x = -0.2, b/R_y = 0.2)$ and $\alpha = 0.0$

Figure 8 Effect of percentage of loaded edge length on instability region of a spherical panel for a/b=1, $a/R_x = b/R_y = 0.2, c/b = 0.2$ and $0.8, \alpha = 0.2$

Figure 9 Effect of position of concentrated load on instability region of a spherical shell for a/b=1, $a/R_x = b/R_y = 0.2$, c/b = 0, 0.25 and 0.5, $\alpha = 0.2$

Answer to the questions and revision of the paper "Parametric Instability of Doubly Curved Panels Subjected to Non-Uniform Harmonic Loading"

by S. K. Sahu and P. K. Datta (Manuscript Reference Number JSV00/096)

Q 1. The parametric stability analysis methodology used by the authors is based on Bolotin's method which is suitable only for harmonic type loadings. As such, "...Non-Uniform loading" in the title may be misleading and should be changed to "...Non-Uniform Harmonic loading".

A. The title of the paper has been changed as suggested by the Reviewer.

Q 2. The authors start the theoretical formulation by considering stability analysis. As a result, how the in-plane loading is included in the shell equations is not presented. The authors should at least present the three equilibrium equations of motion of Sander's with consideration for the external loading.

A. The equilibrium equations of doubly curved panel as per Sander's theory with consideration for external loading has been presented as Equation(1) in section 2.1 in the revised manuscript.

Q 3. The authors present results (Fig 8) where there is partial loading along the boundary edges. However, there is no mention in the formulation how this is done. This should be clearly stated.

A. The formulation of the problem considering the partial edge loading has now been explained in section 2.2 of the revised manuscript.

Q 4. The authors only consider loading in the x-direction. An interesting study that should not entail too much extra work would be to study the effects of double sided (i.e. x and y-directions simultaneously loaded) loading on the instability regions.Would the region sizes increase substantially or would they remain more or less similar? This would be of more interest to readers.

A. The effect of double sided loading on the instability region has been studied as suggested by the Reviewer. The results are presented in Table 3 and conclusions drawn.

5. A. The suggested references along with few current ones have been included in the revised paper.



Figure 10 Effect of percentage of loaded edge length on instability region of a cylindrical panel for a/b=1, $a/R_x = 0, b/R_y = 0.2, c/b = 0.2$ and 0.8, $\alpha = 0.2$



Figure 11 Effect of position of concentrated load on instability region of a cylindrical panel for a/b=1, $a/R_x = 0$, $a/R_y = 0.2$, c/b = 0, 0.25 and 0.5, $\alpha = 0.2$

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Table 4 Non-dimensional critical buckling stresses for the doubly-curved shells/panels.

$$a/b=1, \nu=0.3$$

a/h	a/R_x	b/R_y	Uniaxial loading		Biaxial loading	
			Present FEM Ref [?]		Present FEM	Ref [?]
10	0	0	3.7315	3.7412	1.8658	1.8706
	0.2	0.2	4.1591	4.1630	2.0796	2.0815
	0	0.2	3.8307	3.8391	1.9153	1.9195
	-0.2	0.2	3.7006	3.7100	1.8503	1.8550
20	0	0	3.9288	3.9307	1.9644	1.9654
	0.2	0.2	5.6957	5.6904	2.8479	2.8452
	0	0.2	4.3627	4.3636	2.1814	2.1818
	-0.2	0.2	3.8970	3.9012	1.9485	1.9506

Non dimensional frequency, $\Lambda = \frac{N_x b^2}{\pi^2 D}$

Names of authors: Sri S. K. Sahu

Prof. P. K. Datta

Table 2 Comparison of Non-dimensional frequency for the CFFF doubly curved shells.

Non dimensional frequency, $\omega = \bar{\omega} \sqrt{(\frac{\rho h}{D})}$								
R_y/R_x	Reference	Mode sequence number						
		1	2	3	4			
-1.0	Present FEM	8.2174	9.3882	36.1877	36.3633			
	Liew and Lim [?]	8.2255	9.4091	36.251	36.433			
	Leissa et al. [?]	8.2429	9.4219	36.294	36.503			
-0.5	Present FEM	10.0339	11.1091	37.4797	40.3620			
	Liew and Lim [?]	10.056	11.117	37.559	40.410			
	Leissa et al. [?]	10.062	11.129	37.590	40.430			
0.0	Present FEM	10.5674	16.9768	30.5998	43.1793			
	Liew and Lim [?]	10.589	16.981	30.641	42.211			
	Leissa et al. [?]	10.595	16.991	30.650	42.234			
0.5	Present FEM	10.2579	13.5836	27.5486	37.2232			
	Liew and Lim [?]	10.284	13.606	27.608	37.020			
	Leissa et al. [?]	10.295	13.628	27.624	37.048			
1.0	Present FEM	8.9856	9.7314	30.3317	33.8534			
	Liew and Lim [?]	9.0054	9.7612	30.404	33.943			
	Leissa et al. [?]	9.0327	9.7809	30.476	33.998			

 $a/b = 1, b/h = 100, b/R_y = 0.5$, and $\nu = 0.3$

Names of authors: Sri S. K. Sahu

Prof. P. K. Datta