

# Multi-point Geostatistical Simulation by Applying Quadratic Optimization Algorithm

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# Multi-point simulation

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- **Statistical-based algorithm**
  - Neural Network (Caers 2001)
  - SNESIM (Strebelle 2002)
  - Markov Random field (Daly 2004)
  - Markov Mesh Model (Kjønsberg & Kolbjørnsen 2008)
  - HOSIM (Mustapha and Dimitrakopoulos 2010)
  
- **Pattern-based algorithm**
  - Simpat (Arpat and Cares 2007)
  - Filtersim (Zhang et al. 2006;)
  - Multi-dimensional scaling (Honarkhah & Caers 2010)
  - Wavesim (Chatterjee et al. 2012)
  - CDF-based (Mustapha et al. 2011)
  - SOM-based (Chatterjee & Roussos, 2011)

# Multi-point simulation

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- The problem with all pattern-based simulation algorithm is that it is highly dependence on pattern frequencies in the training image
- The problem is not with the patterns seen in the training image rather, with how the method treats patterns that are not present in the training image
- Statistical models can interpolate between observed patterns to compute the probability of patterns that are not present in the training image

# Regression model using SVM

1	1	1
1	1	0
1	1	0
0	1	0
0	1	0
0	1	0

**X**

0
1
0
1
0
0

**y**

$$\max \Psi(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i,j=1}^N y_i \alpha_i y_j \alpha_j K_{ij}$$

$$\sum_{i=1}^N y_i \alpha_i = 0$$

$$0 \leq \alpha_i \leq C$$

$$K_{ij} = K(\mathbf{x}_i, \mathbf{x}_j)$$

$$f(\mathbf{x}, \mathbf{w}) = \sum_{j=1}^k w_j g_j(\mathbf{x}) + b$$

$$L_\varepsilon(y, f(\mathbf{x}, \mathbf{w})) = \begin{cases} 0 & \text{if } |y - f(\mathbf{x}, \mathbf{w})| \leq \varepsilon \\ |y - f(\mathbf{x}, \mathbf{w})| - \varepsilon & \text{otherwise} \end{cases}$$

$$\text{Min } \frac{1}{2} \|\omega\|^2 + C \sum_{i=1}^N (\xi_i + \xi_i^*)$$

$$\begin{cases} y_i - f(\mathbf{x}_i, \omega) \leq \varepsilon + \xi_i^* \\ f(\mathbf{x}_i, \omega) - y_i \leq \varepsilon + \xi_i \\ \xi_i, \xi_i^* \geq 0, i = 1, \dots, N \end{cases}$$

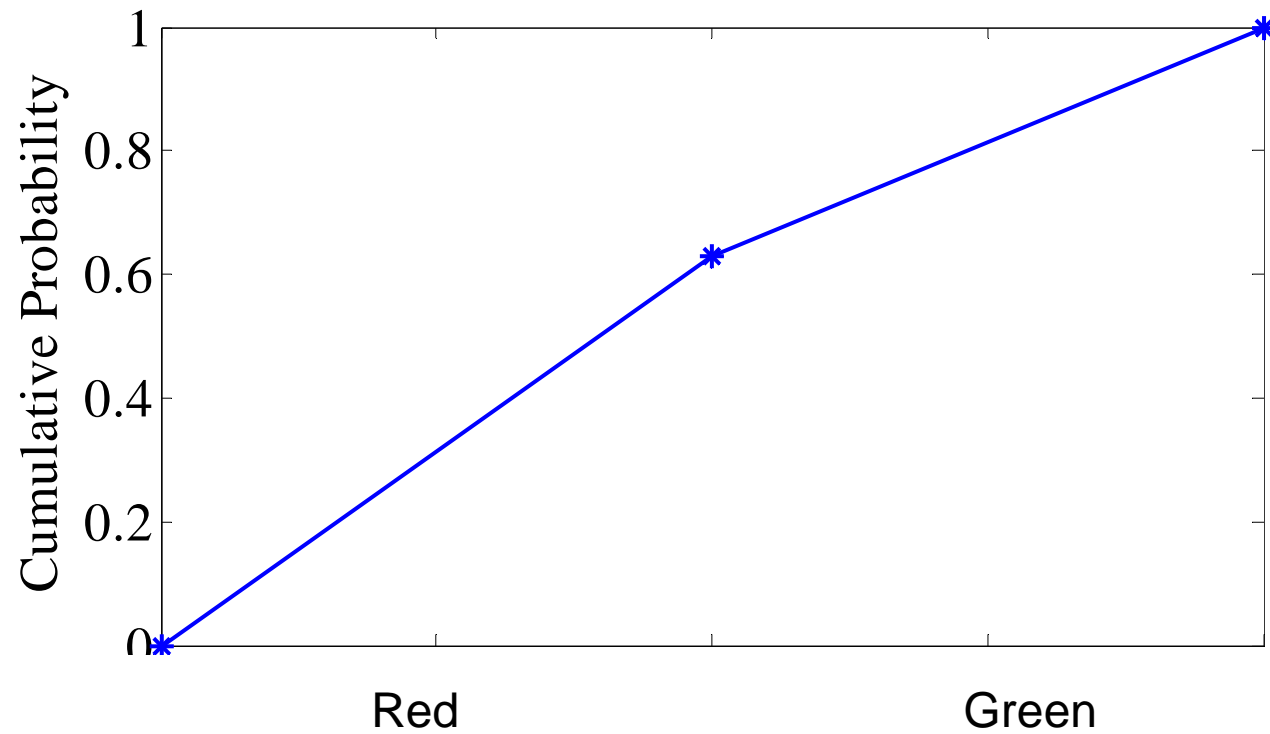
$$K(x, x_i) = \exp(-\|x - x_i\|^2 / \sigma^2)$$

$$f(\mathbf{x}) = \sum_{i=1}^{n_{sv}} (\alpha_i - \alpha_i^*) K(\mathbf{x}_i, \mathbf{x})$$

# Calculating the CCDF

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$$f(x) = 0.631$$

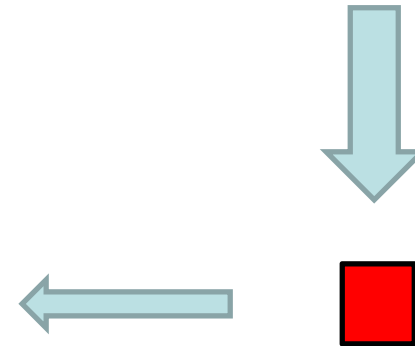
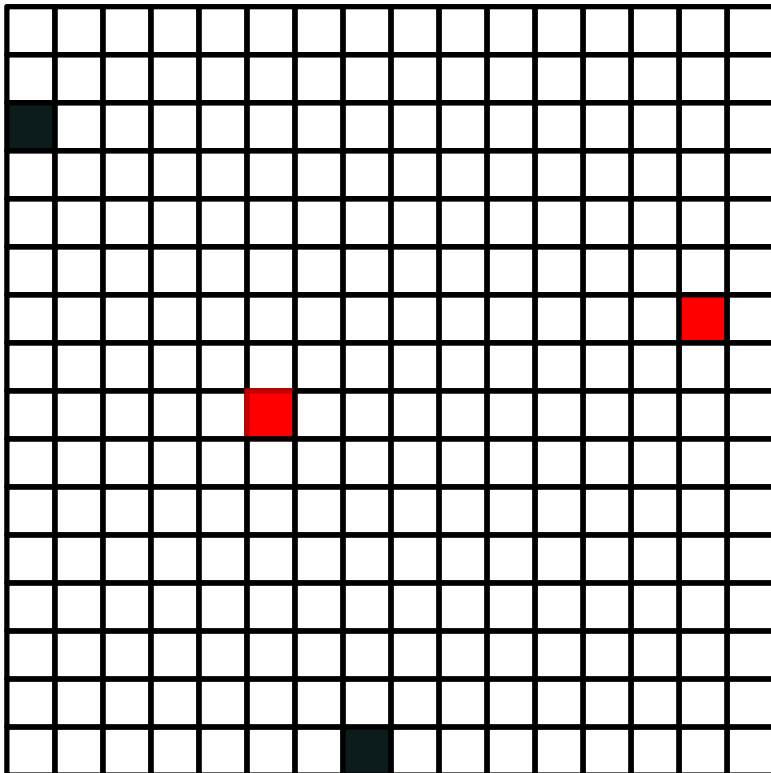
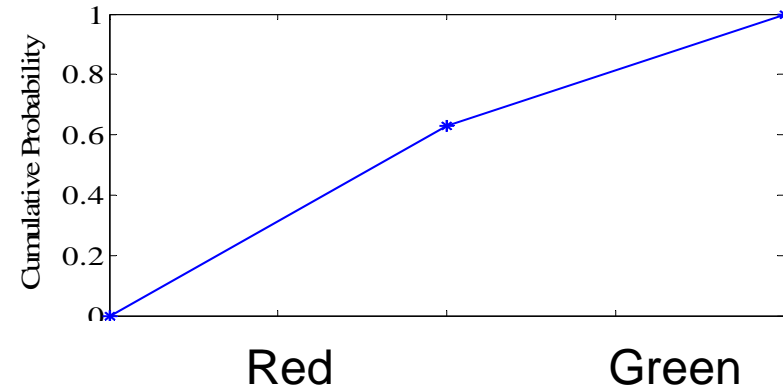


# Calculating the CCDF

Draw a Uniform  
Random number



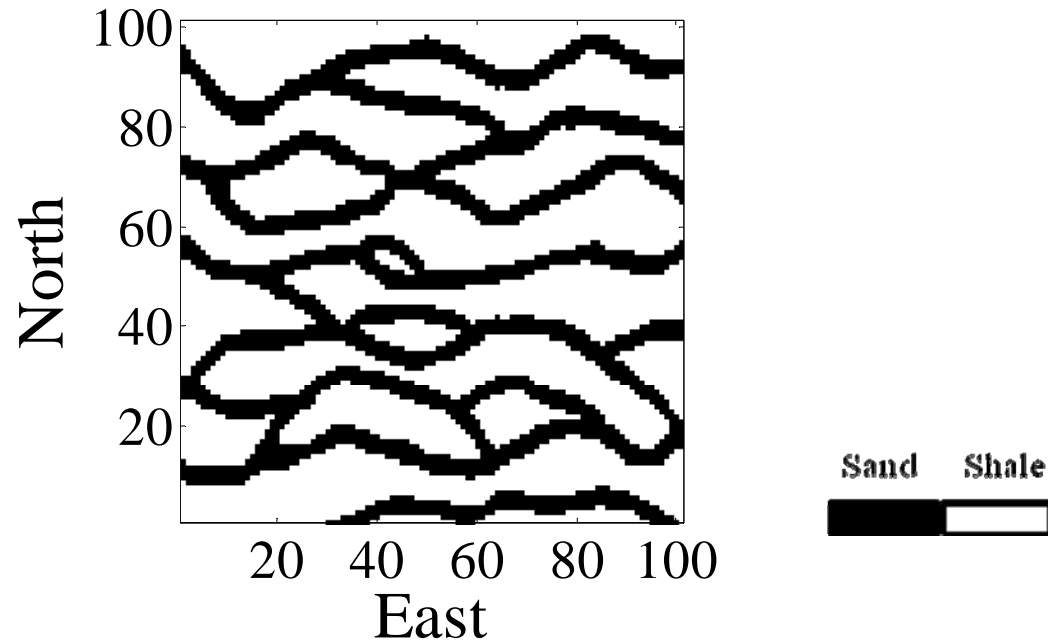
0.2551



# Validation of the method

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Unconditional simulation with binary image

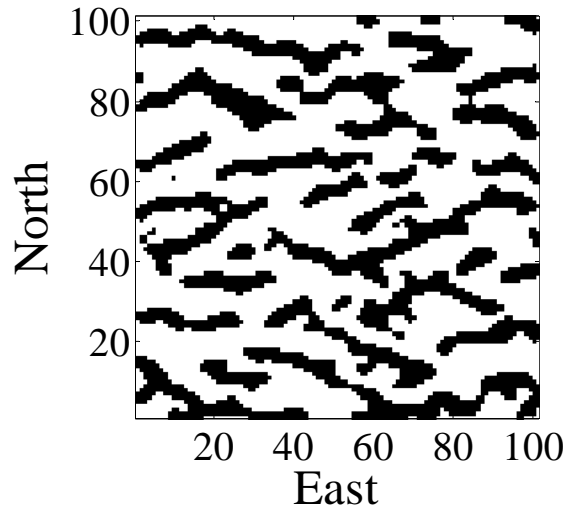


Training image

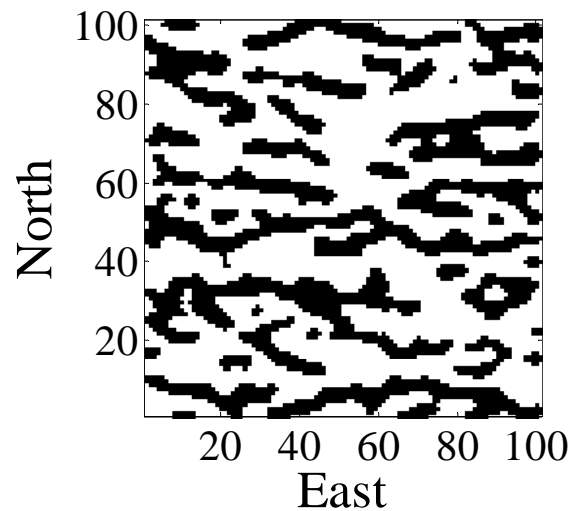
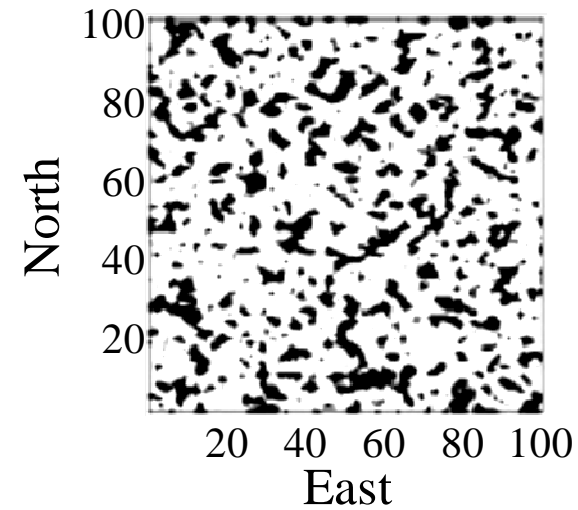
# Validation of the method

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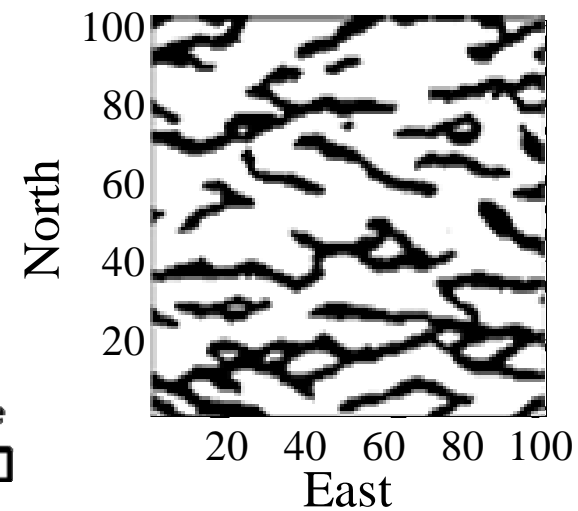
Our proposed approach



Snesim with single grid



Snesim with 3 multi-grid

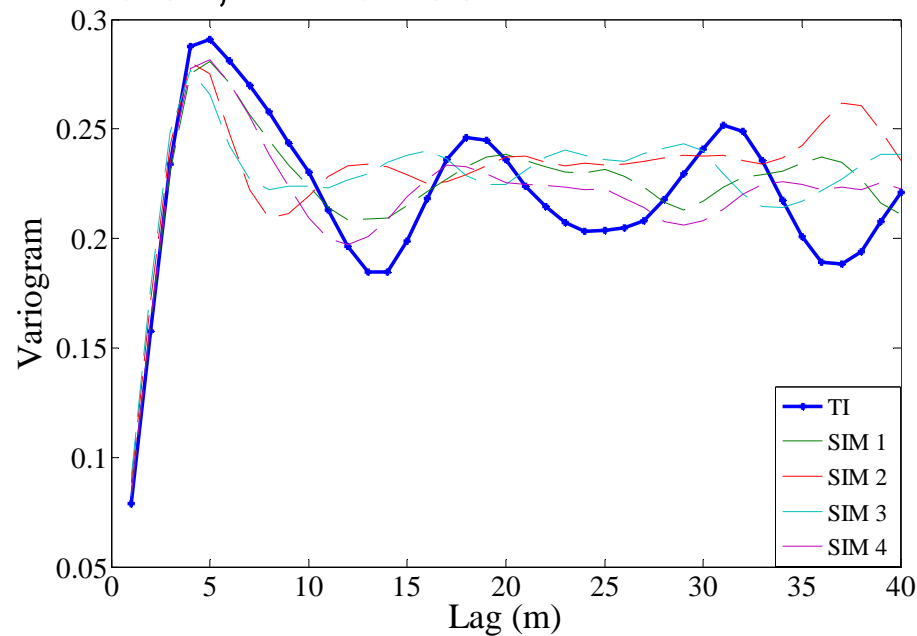




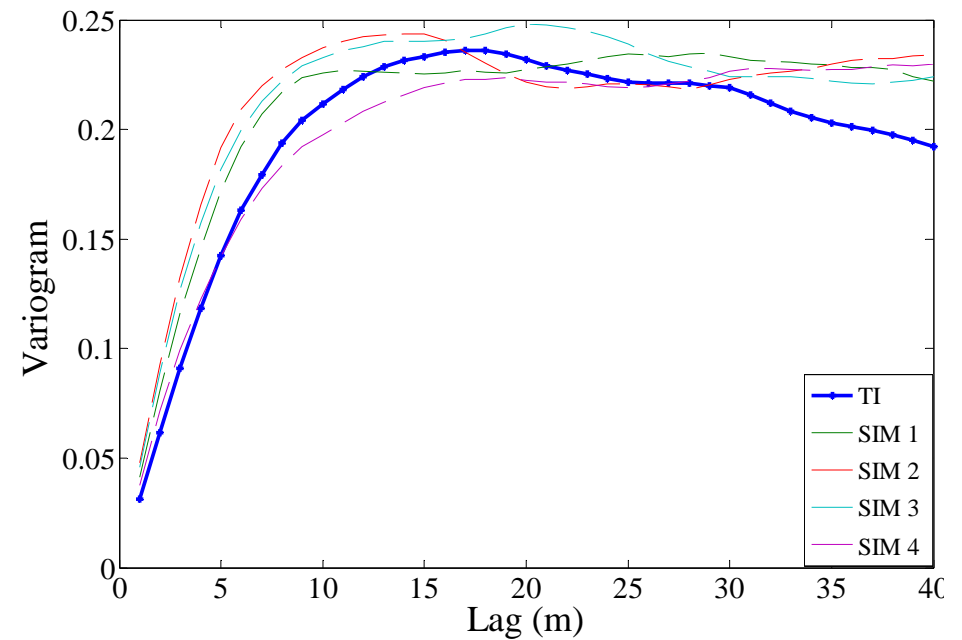
# Reproduction of statistics

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- The proportion of sand and shale in TI are 0.325, and 0.675
- The proportions of sand in 4 realisations of our proposed method are 0.317, 0.329, 0.321, and 0.33
- The proportions of sand in four realisations of snesim are 0.28, 0.289, 0.31, and 0.298



(a) Variogram E-W



(b) Variogram N-S

# Conclusions

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- A new multi-pint simulation algorithm is proposed
- SVM model was solved by QP to generate the *ccdf* at unknown point
- The indicators transformed of the pattern database are used to calculate the probability value of specific threshold
- The probability values at different threshold are used to calculate the *ccdf*.
- The algorithm is verified by two- dimensional conditional and unconditional simulation

# Conclusions

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- The advantage of the algorithm is that the chances of reproduction of statistics are much better than filtersim as well as snesim.
- The main limitation of the proposed algorithm is that the computational time is significantly high
- Mapping the high dimensional conditioning data into another domain with significantly less number of mapped data while preserving the data variability may reduce the computational time

Thank you